Neural network approximation for superhedging prices

Abstract

This article examines neural network-based approximations for the superhedging price process of a contingent claim in a discrete time market model. First we prove that the $\alpha$-quantile hedging price converges to the superhedging price at time 0 for $\alpha$ tending to 1, and show that the $\alpha$-quantile hedging price can be approximated by a neural network-based price. This provides a neural network-based approximation for the superhedging price at time 0 and also the superhedging strategy up to maturity. To obtain the superhedging price process for $t > 0$, by using the Doob decomposition it is sufficient to determine the process of consumption. We show that it can be approximated by the essential supremum over a set of neural networks. Finally, we present numerical results.

Keywords: Deep learning; Superhedging; Quantile hedging

1 Introduction

In this paper we study neural network approximations for the superhedging price process for a contingent claim in discrete time.

Superhedging was first introduced in (El Karoui & Quenez, 1995) and then thoroughly studied in various settings and market models. It is impossible to cover the complete literature here, but we name just a few references. For instance, in continuous time, for general càdlâg processes we mention (Kramkov, 1996), for robust superhedging (Nutz, 2015), (Touzi, 2014), for pathwise superhedging on prediction sets (Bartl, Kupper, Neufeld, 2020), (Bartl, Kupper, Prömel, Tangpi, 2019), or for superhedging under proportional transaction costs (Campi & Schachermayer, 2006), (Cvitanic & Karatzas, 1996), (Kabanov & Last, 2002), (Schachermayer, 2014), (Soner, Shreve, Cvitanic, et al., 1995). Also in discrete time there are various studies in the literature, like the standard case (Föllmer & Schied, 2016), robust superhedging (Carassus, Oblój, Wiesel, 2019), (Oblój & Wiesel, 2021), superhedging under volatility uncertainty (Nutz & Soner, 2012), or model-free superhedging (Burzoni, Frittelli, Maggis, et al., 2017). The superhedging price provides an opportunity to secure a claim, but it may be too high or reduce the probability to profit from the option. In order to solve this problem, quantile hedging was introduced in (Föllmer & Leukert, 1999), where the authors propose to either fix the initial capital and maximize the probability of superhedging with this capital or fix a probability of
superhedging and minimize the required capital. In this way a trader can determine the desired trade-off between costs and risk.

In certain situations it is possible to calculate explicitly or recursively the superhedging or quantile hedging price, see e.g. (Carassus, Gobet, & Temam, 2007), but in general incomplete markets it may be complicated to determine superhedging prices or quantile hedging prices. In this article we investigate neural network-based approximations for quantile- and superhedging prices. Neural network-based methods have been recently introduced in financial mathematics, for instance for hedging derivatives, see (Buehler, Gonon, Teichmann, & Wood, 2019), determining stopping times, see (Becker, Cheridito, & Jentzen, 2019), or calibration of stochastic volatility models, see (Cuchiero, Khosrawi, & Teichmann, 2020), and many more. For an overview of applications of machine learning to hedging and option pricing we refer to (Ruf & Wang, 2020) and the references therein.

This paper contributes to the literature on hedging in discrete time market models in several ways. First, we prove that the $\alpha$-quantile hedging price converges to the superhedging price for $\alpha$ tending to 1. Further, we show that it is feasible to approximate the $\alpha$-quantile hedging and thus also the superhedging price for $t = 0$ by neural networks. We extend our machine learning approach also to approximate the superhedging price process for $t > 0$. By the first step we obtain an approximation for the superhedging strategy on the whole interval up to maturity. By using the uniform Doob decomposition, see (Föllmer & Schied, 2016), we then only need to approximate the process of consumption $B$ to generate the superhedging price process. We prove that $B$ can be obtained as the the essential supremum over a set of neural networks.

Finally, we present and discuss numerical results for the proposed neural network methods.

The paper is organized as follows. In Section 2, we present the discrete time market model of (Föllmer & Schied, 2016) and recall essential definitions and results on superhedging. Section 3 contains the study of the superhedging price for $t = 0$. More specifically, in Section 3.1 we prove in Theorem 3.4 that the $\alpha$-quantile hedging price converges to the superhedging price as $\alpha$ tends to 1. We also present a similar result in Corollary 3.9 in Section 3.1.2, where $\alpha$-quantile hedging is given in terms of success ratios. In Section 3.2 we show in Theorem 3.13 that the superhedging price can be approximated by neural networks. This concludes the approximation for $t = 0$. Then, we consider the case for $t > 0$ in Section 4. In Section 4.1, we explain how
the uniform Doob decomposition can be used to approximate the superhedging price process. In that account, we prove an explicit representation of the process of consumption, see Proposition 4.1. Proposition 4.3 and Theorem 4.4 show that the process of consumption and thus the superhedging price process can be approximated by neural networks. The numerical results are presented in Section 5. The section is divided in the case $t = 0$, see Section 5.1, and $t > 0$, see Section 5.2. We present details on the algorithm and the implementation. Appendix B contains a version of the universal approximation theorem, derived from (Hornik, 1991).

2 Preliminaries

In this section we introduce the discrete time financial market model from (Föllmer & Schied, 2016) and recall some basic notions on superhedging.

Consider a finite time horizon $T > 0$. Let $(\Omega, \mathcal{F}, \mathbb{P})$ be a probability space endowed with a filtration $\mathbb{F} := (\mathcal{F}_t)_{t=0,1,...,T}$. Further, we suppose that $\mathcal{F} = \mathcal{F}_T$ and that $\mathcal{F}_0$ is constant $\mathbb{P}$-a.s. Then $\mathcal{F}_0 = \{\emptyset, \Omega\}$.

In our market model on $(\Omega, \mathcal{F}, \mathbb{F}, \mathbb{P})$ the asset prices are modeled by a non-negative, adapted, stochastic process $\bar{S} = (S^0, \bar{S}) = (S^0_t, S^1_t, \ldots, S^d_t)_{t=0,1,...,T}$, with $d \geq 1$, $d \in \mathbb{N}$. Further, we assume that $S^0_t > 0$ $\mathbb{P}$-a.s. for all $t = 0, 1, \ldots, T$. The discounted price process $\bar{X} = (X^0, X) = (X^0_t, X^1_t, \ldots, X^d_t)_{t=0,1,...,T}$ is given by

$$X^i_t := \frac{S^i_t}{S^0_t}, \; t = 0, 1, \ldots, T, \; i = 0, \ldots, d.$$  

We denote by $\mathcal{P}$ the set of all equivalent martingale measures for $X$ and assume $\mathcal{P} \neq \emptyset$. By Theorem 5.16 of (Föllmer & Schied, 2016) this is equivalent to the market model being arbitrage-free.

Definition 2.1. A trading strategy is a predictable $\mathbb{R}^{d+1}$-valued stochastic process $\tilde{\xi} = (\tilde{\xi}^0, \xi) = (\xi^0_t, \xi^1_t, \ldots, \xi^d_t)_{t=1,...,T}$ with (discounted) value process $V = (V_t)_{t=0,.,T}$ given by

$$V_0 := \tilde{\xi}_1 \cdot \bar{X}_0 \quad \text{and} \quad V_t := \tilde{\xi}_t \cdot \bar{X}_t \; \text{for} \; t = 1, \ldots, T.$$  


A trading strategy $\tilde{\xi}$ is called self-financing if

$$\tilde{\xi}_t \cdot \tilde{S}_t = \tilde{\xi}_{t+1} \cdot \tilde{S}_t \quad \text{for } t = 1, \ldots, T - 1.$$ 

A self-financing trading strategy is called an \textit{admissible strategy} if its value process satisfies $V_T \geq 0$.

By $\mathcal{A}$ we denote the set of all admissible strategies $\tilde{\xi}$ and by $\mathcal{V}$ the associated value processes, i.e.,

$$\mathcal{V} := \{V = (V_t)_{t=0,1,\ldots,T} : V_0 = \tilde{\xi}_1 \cdot \tilde{X}_0, V_t = \tilde{\xi}_t \cdot \tilde{X}_t \text{ for } t = 1, \ldots, T, \text{ and } \tilde{\xi} \in \mathcal{A}\}$$

A discounted European contingent claim is represented by a non-negative, $\mathcal{F}_T$-measurable random variable $H$ such that $\operatorname{supp}_{\mathcal{P}^*} \mathbb{E}^*[H] < \infty$.

\textbf{Definition 2.2.} Let $H$ be a European contingent claim. A self-financing trading strategy $\tilde{\xi}$ whose value process $V$ satisfies

$$V_T \geq H \quad \mathcal{P}\text{-a.s.}$$

is called a \textit{superhedging strategy} for $H$. In particular, any superhedging strategy is admissible since $H \geq 0$ by definition.

The upper Snell envelope for a discounted European claim $H$ is defined by

$$U^+_t(H) = U^+_t := \operatorname{ess sup}_{\mathcal{P}^*} \mathbb{E}^*[H \mid \mathcal{F}_t], \quad \text{for } t = 0, 1, \ldots, T.$$ 

Set

$$\mathcal{U}_t := \left\{ \tilde{U}_t \in L^0(\Omega, \mathcal{F}_t, \mathcal{P}) : \exists \tilde{\xi} \text{ pred. s.t. } \tilde{U}_t + \sum_{k=t+1}^{T} \tilde{\xi}_k \cdot (X_k - X_{k-1}) \geq H \quad \mathcal{P}\text{-a.s.} \right\}. \quad (2.1)$$

In the sequel $\operatorname{ess inf} \mathcal{U}_t$ denotes the essential infimum of the set of random variables $\mathcal{U}_t$ which is defined by Theorem A.37 and Definition A.38 of (Föllmer & Schied, 2016), see also Appendix C.

\textbf{Corollary 2.3} (Corollary 7.3, Theorem 7.5, Corollary 7.15, (Föllmer & Schied, 2016)). The
process
\[
\left( \operatorname{ess} \sup_{P^* \in \mathcal{P}} E^*[H \mid \mathcal{F}_t] \right)_{t=0,1,\ldots,T},
\]
is the smallest \( \mathcal{P} \)-supermartingale whose terminal value dominates \( H \). Furthermore, there exists an adapted increasing process \( B = (B_t)_{t=0,\ldots,T} \) with \( B_0 = 0 \) and a \( d \)-dimensional predictable process \( \xi = (\xi_t)_{t=1,\ldots,T} \) such that
\[
\operatorname{ess} \sup_{P^* \in \mathcal{P}} E^*[H \mid \mathcal{F}_t] = \sup_{P^* \in \mathcal{P}} E^*[H] + \sum_{k=1}^{t} \xi_k \cdot (X_k - X_{k-1}) - B_t \quad \mathcal{P} \text{-a.s. for all } t = 0, \ldots, T. \tag{2.2}
\]
Moreover, \( \operatorname{ess} \sup_{P^* \in \mathcal{P}} E^*[H \mid \mathcal{F}_t] = \inf \mathcal{U}_t \) and
\[
\operatorname{ess} \sup_{P^* \in \mathcal{P}} E^*[H \mid \mathcal{F}_t] + \sum_{k=t+1}^{T} \xi_k \cdot (X_k - X_{k-1}) \geq H, \quad \text{for all } t = 0, \ldots, T. \tag{2.3}
\]
The process \( B \) in (2.2) is sometimes called process of consumption, see (Kramkov, 1996). Equations (2.2) and (2.3) yield
\[
\sup_{P^* \in \mathcal{P}} E^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \geq B_t \geq B_{t-1} \geq 0 \quad \text{for all } t = 1, \ldots, T. \tag{2.4}
\]
Corollary 7.18 of (Föllmer & Schied, 2016) and (2.3) guarantee that \( U^+_t \) is the minimal amount needed at time \( t \) to start a superhedging strategy and thus there exists a predictable process \( \xi \) such that
\[
\operatorname{ess} \sup_{P^* \in \mathcal{P}} E^*[H \mid \mathcal{F}_t] + \sum_{k=t+1}^{T} \xi_k \cdot (X_k - X_{k-1}) \geq H.
\]
Further, \( U^+_0 \) is called the superhedging price at time \( t = 0 \) of \( H \) and coincides with the upper bound of the set of arbitrage-free prices.

3 Superhedging price for \( t = 0 \)

In this section we approximate the superhedging price for \( t = 0 \) in two steps. In the first part, we introduce the theory of quantile hedging, see (Föllmer & Leukert, 1999). In Theorem 3.4
we prove that the quantile hedging price for $\alpha \in (0, 1)$ converges to the superhedging price as $\alpha$ tends to 1. Analogously, in Corollary 3.9 we prove that for $\alpha$ tending to 1 also the success ratios for $\alpha \in (0, 1)$ converge to the superhedging price.

In the second part, we prove in Theorem 3.13 that the superhedging price and the associated strategies can be approximated by neural networks.

### 3.1 Quantile hedging

#### 3.1.1 Success sets

In incomplete markets perfect replication of a contingent claim may not be possible. Superhedging offers an alternative hedging method but it presents two main disadvantages. On the one hand investing by using the superhedging strategy may reduce the possibility to profit. On the other hand, the superhedging price may result to be too high.

Quantile hedging was proposed for the first time in (Föllmer & Leukert, 1999) to address these problems. Fix $\alpha \in (0, 1)$. Given probability of success $\alpha \in (0, 1)$ we consider the minimization problem

$$\inf \mathcal{L}_0^\alpha := \inf \{ u \in \mathbb{R} : \exists \xi = (\xi_t)_{t=1,...,T} \text{ predictable process with values in } \mathbb{R}^d \text{ such that}$$

$$(u, \xi) \text{ is admissible and } \mathbb{P}\left( u + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) \geq H \right) \geq \alpha \}.$$  \hspace{1cm} (3.1)

Here $1 - \alpha$ is called the shortfall probability. Quantile hedging may be considered as a dynamic version of the value at risk concept.

For an admissible strategy $(u, \xi)$ with associated value process $V$, we call

$$\{ V_T \geq H \}$$

the *success set*.

**Remark 3.1.** Note that in (3.1) we need to require that $(u, \xi)$ is admissible since this is not automatically implied by the definition of quantile hedging as in the case of superhedging strategies in Definition 2.2.
Proposition 3.2 below provides an equivalent formulation of quantile hedging (3.1), see also (Föllmer & Leukert, 1999). The proof is given in Appendix A.

Proposition 3.2. Fix \( \alpha \in (0, 1) \). Then

\[
\inf \mathcal{U}_0^\alpha = \inf \left\{ \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H \mathbb{1}_A] : A \in \mathcal{F}_T, \ P(A) \geq \alpha \right\}.
\]

Corollary 7.15 of (Föllmer & Schied, 2016) guarantees that there exists a superhedging strategy with initial value \( \inf \mathcal{U}_0 \). In contrast, there might be no explicit solution to the quantile hedging approach (3.1). If a solution to the quantile hedging approach exists, then Proposition 3.2 states that it is given by the solution of the classical hedging formulation for the knockout option \( H \mathbb{1}_A \) for some suitable \( A \in \mathcal{F}_T \). However, such a set \( A \in \mathcal{F}_T \) does not always exist. In particular, quantile hedging does not always admit an explicit solution in general. The Neyman-Pearson lemma suggests to consider so-called success ratios instead of success sets. We will briefly discuss success ratios below. For further information we refer the interested reader to (Föllmer & Leukert, 1999).

We now show that the superhedging price \( \inf \mathcal{U}_0 \), can be approximated by the quantile hedging price \( \inf \mathcal{U}_0^\alpha \) for \( \alpha \) tending to 1.

Definition 3.3. For \( \alpha \in (0, 1) \) we define

\[
\mathcal{F}^\alpha := \{ A \in \mathcal{F}_T : P(A) \geq \alpha \}.
\]

Theorem 3.4. The \( \alpha \)-quantile hedging price converges to the superhedging price as \( \alpha \) tends to 1, i.e.,

\[
\inf \mathcal{U}_0^\alpha \xrightarrow{\alpha \uparrow 1} \inf \mathcal{U}_0.
\]

We assume \( \mathcal{F}_t = \sigma(Y_0, \ldots, Y_t) \) for \( t = 0, \ldots, T \) and for some \( \mathbb{R}^m \)-valued process \( Y = (Y_t)_{t=0, \ldots, T} \) for some \( m \in \mathbb{N} \), and write \( \mathcal{G}_t = (Y_0, \ldots, Y_t) \) for \( t \geq 0 \).

Proof. We first note that, using Proposition 3.2 it suffices to prove

\[
\inf_{A \in \mathcal{F}^\alpha} \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H \mathbb{1}_A] \xrightarrow{\alpha \uparrow 1} \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H].
\]
Let \((\alpha_n)_{n \in \mathbb{N}} \subset (0, 1)\) be an increasing sequence such that \(\alpha_n\) converges to 1 as \(n\) tends to infinity.

Note that
\[
\inf_{A \in \mathcal{F}^n} \sup_{p \in P} E^*[H 1_A] \leq \inf_{A \in \mathcal{F}^{n+1}} \sup_{p \in P} E^*[H 1_A] \leq \sup_{p \in P} E^*[H],
\]
(3.2)
because \(\mathcal{F}^{n+1} \subset \mathcal{F}^n\). Therefore, the limit of \((\inf_{A \in \mathcal{F}^n} \sup_{p \in P} E^*[H 1_A])_{n \in \mathbb{N}}\) exists because the sequence is monotone and bounded. Let \(\varepsilon > 0\) be arbitrary. For each \(n \in \mathbb{N}\) there exists \(A_n \in \mathcal{F}^n\) such that
\[
\inf_{A \in \mathcal{F}^n} \sup_{p \in P} E^*[H 1_A] \leq \sup_{p \in P} E^*[H 1_{A_n}] < \inf_{A \in \mathcal{F}^n} \sup_{p \in P} E^*[H 1_A] + \varepsilon.
\]
(3.3)

Then, by Lemma 1.70 of (Föllner & Schied, 2016) there exists a sequence \(\psi_n \in \text{conv}\{1_{A_n}, 1_{A_{n+1}}, \ldots\}\), \(n \in \mathbb{N}\), which converges \(P\)-a.s. to some \(\psi \in L^\infty(\Omega, \mathcal{F}_T, P; [0, 1])\). Note that it is not clear if \(\psi\) is an indicator function of some \(\mathcal{F}_T\)-measurable set. We will show that \(\psi = 1\) \(P\)-a.s. For \(n \in \mathbb{N}\), \(\psi_n\) is of the form
\[
\psi_n = \sum_{k=n}^{\infty} \lambda^n_k 1_{A_k},
\]
(3.4)
for some \((\lambda^n_k)_{k=n}^{\infty} \geq 0\) such that \(\sum_{k=n}^{\infty} \lambda^n_k = 1\), where for each \(n \in \mathbb{N}\) only finitely many \(\lambda^n_k\) are non-zero. By dominated convergence and (3.4) we obtain
\[
E_P[\psi] = \lim_{n \to \infty} E_P[\psi_n] = \lim_{n \to \infty} E_P \left[ \sum_{k=n}^{\infty} \lambda^n_k 1_{A_k} \right] = \lim_{n \to \infty} \left( \sum_{k=n}^{\infty} \lambda^n_k E_P[1_{A_k}] \right).
\]
(3.5)

Because \(\sum_{k=n}^{\infty} \lambda^n_k = 1\) and by the definition of the limes inferior, equation (3.5) yields
\[
E_P[\psi] \geq \lim_{n \to \infty} \left( \sum_{k=n}^{\infty} \lambda^n_k \inf_{p \in P} E_p[1_{A_k}] \right) = \lim_{n \to \infty} \left( \inf_{p \in P} E_p[1_{A_k}] \right)
\]
\[
= \lim \inf_{n \to \infty} E_P[1_{A_n}] = \lim \inf_{n \to \infty} P(A_n) \geq \lim \inf_{n \to \infty} \alpha_n = 1.
\]
(3.6)

Since \(0 \leq \psi \leq 1\), it follows that \(\psi = 1\) \(P\)-a.s. By (3.3) and with similar arguments as in (3.5) and (3.6) using the supremum instead of the infimum, we obtain by dominated convergence for
any \( \bar{P}^* \in \mathcal{P} \) that
\[
\limsup_{n \to \infty} \left( \inf_{A \in \mathcal{F}^n} \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H_1 A] + \varepsilon \right) \geq \limsup_{n \to \infty} \sup_{P^* \in \mathcal{P}} \mathbb{E}[H_1 A_n] \\
\geq \lim_{n \to \infty} \mathbb{E}_{P^*} [H_{\psi_n}] = \mathbb{E}^*[H_{\psi}] = \mathbb{E}_{P^*} [H].
\] (3.7)

Since the limit on the left hand side in (3.7) exists by (3.2) and (3.7) holds for all \( \bar{P}^* \in \mathcal{P} \), we get
\[
\lim_{n \to \infty} \left( \inf_{A \in \mathcal{F}^n} \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H_1 A] + \varepsilon \right) \geq \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H].
\] (3.8)

Thus, we observe that (3.2) and (3.8) yields
\[
\lim_{n \to \infty} \left( \inf_{A \in \mathcal{F}^n} \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H_1 A] \right) \leq \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H] \leq \lim_{n \to \infty} \left( \inf_{A \in \mathcal{F}^n} \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H_1 A] + \varepsilon \right).
\]

As \( \varepsilon > 0 \) was arbitrary this implies that
\[
\lim_{n \to \infty} \left( \inf_{A \in \mathcal{F}^n} \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H_1 A] \right) = \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H].
\]

\[ \square \]

### 3.1.2 Success ratios

Let \( \mathcal{R} := L^\infty(\Omega, \mathcal{F}_T, P; [0, 1]) \) be the set of randomized tests. For \( \alpha \in (0, 1) \) we denote by \( \mathcal{R}^\alpha \) the set
\[
\mathcal{R}^\alpha := \{ \varphi \in \mathcal{R} : \mathbb{E}_P[\varphi] \geq \alpha \}.
\]

We now consider the following minimization problem
\[
\inf \left\{ \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H \varphi] : \varphi \in \mathcal{R}^\alpha \right\}. \tag{3.9}
\]

In a first step, we prove that this problem admits an explicit solution. In a second step, we show that the solution is given by the so-called success ratio, see Definition 3.6 below. In particular, (3.9) can be formulated in terms of success ratios, see also (Föllmer & Leukert, 1999). In
Proposition 3.5 and 3.8 we provide a proof for some result of (Föllmer & Leukert, 1999) for the sake of completeness.

**Proposition 3.5.** There exists a randomized test \( \tilde{\varphi} \in \mathcal{R} \) such that

\[
\mathbb{E}_P[\tilde{\varphi}] = \alpha,
\]

and

\[
\inf_{\varphi \in \mathcal{R}^\alpha} \sup_{P' \in \mathcal{P}} \mathbb{E}^*[H \varphi] = \sup_{P' \in \mathcal{P}} \mathbb{E}^*[H \tilde{\varphi}].
\]

(3.10)

**Proof.** Take a sequence \( (\varphi_n)_{n \in \mathbb{N}} \subset \mathcal{R}^\alpha \) such that

\[
\lim_{n \to \infty} \sup_{P' \in \mathcal{P}} \mathbb{E}^*[H \varphi_n] = \inf_{\varphi \in \mathcal{R}^\alpha} \sup_{P' \in \mathcal{P}} \mathbb{E}^*[H \varphi].
\]

(3.11)

By Lemma 1.70 of (Föllmer & Schied, 2016) there exists a sequence of convex combinations \( \tilde{\varphi}_n \in \text{conv}\{\varphi_n, \varphi_{n+1}, \ldots\} \) converging \( P \)-a.s. to a function \( \tilde{\varphi} \in \mathcal{R} \) because \( \varphi_n \in [0,1] \) for all \( n \in \mathbb{N} \). Clearly \( \tilde{\varphi}_n \in \mathcal{R}^\alpha \) for each \( n \in \mathbb{N} \). Hence, dominated convergence yields that

\[
\mathbb{E}_P[\tilde{\varphi}] = \lim_{n \to \infty} \mathbb{E}_P[\tilde{\varphi}_n] \geq \alpha,
\]

(3.12)

and we get that \( \tilde{\varphi} \in \mathcal{R}^\alpha \). In the following we use similar arguments as in the proof of Theorem 3.4. In particular, \( \tilde{\varphi}_n \) is of the form

\[
\tilde{\varphi}_n = \sum_{k=n}^{\infty} \lambda_k^n \varphi_k,
\]

(3.13)

for some \( (\lambda_k)_{k=n}^{\infty} \) such that \( \sum_{k=n}^{\infty} \lambda_k^n = 1 \), where for each \( n \in \mathbb{N} \) only finitely many \( \lambda_k^n \) are non-zero. By (3.13) we obtain for any \( P^* \in \mathcal{P} \) that

\[
\limsup_{n \to \infty} \mathbb{E}_{P^*}[H \varphi_n] = \lim_{n \to \infty} \left( \sup_{k \geq n} \mathbb{E}_{P^*}[H \varphi_k] \right) \geq \lim_{n \to \infty} \left( \sum_{k=n}^{\infty} \lambda_k^n \mathbb{E}_{P^*}[H \varphi_k] \right)
\]

\[
= \lim_{n \to \infty} \mathbb{E}_{P^*}[H \tilde{\varphi}_n] = \mathbb{E}_{P^*}[H \tilde{\varphi}],
\]

(3.14)

where we used monotone convergence. Moreover, we obtain by (3.11), (3.14) and dominated
convergence that
\[
\inf_{\phi \in \mathbb{R}^n} \sup_{P^* \in P} \mathbb{E}^*[H\phi] = \lim_{n \to \infty} \sup_{P^* \in P} \mathbb{E}^*[H\phi_n] \geq \lim_{n \to \infty} \mathbb{E}^*[H\phi_n] \geq \lim_{n \to \infty} \mathbb{E}^*[H\tilde{\phi}_n] = \mathbb{E}^*[H\tilde{\phi}].
\] (3.15)

Since (3.15) holds for all \( P^* \in \mathcal{P} \) we obtain
\[
\inf_{\phi \in \mathbb{R}^n} \sup_{P^* \in P} \mathbb{E}^*[H\phi] \geq \sup_{P^* \in P} \mathbb{E}^*[H\tilde{\phi}].
\]

Furthermore, \( \tilde{\phi} \in \mathcal{R}^\alpha \) by (3.12) yields
\[
\inf_{\phi \in \mathbb{R}^n} \sup_{P^* \in P} \mathbb{E}^*[H\phi] = \sup_{P^* \in P} \mathbb{E}^*[H\tilde{\phi}].
\]
So \( \tilde{\phi} \) is the desired minimizer.

We now show that \( \mathbb{E}_P[\tilde{\phi}] = \alpha \) holds. If \( \mathbb{E}_P[\tilde{\phi}] > \alpha \), then we can find \( \varepsilon > 0 \) such that \( \phi_{\varepsilon} := (1 - \varepsilon)\tilde{\phi} \in \mathcal{R}^\alpha \), and
\[
\sup_{P^* \in P} \mathbb{E}^*[H\phi_{\varepsilon}] = (1 - \varepsilon) \sup_{P^* \in P} \mathbb{E}^*[H\tilde{\phi}] < \sup_{P^* \in P} \mathbb{E}^*[H\tilde{\phi}],
\] (3.16)
which contradicts the minimality property of \( \tilde{\phi} \). Thus,
\[
\mathbb{E}_P[\tilde{\phi}] = \alpha.
\]

**Definition 3.6.** For an admissible strategy with value process \( V \in \mathcal{V} \) we define its success ratio by
\[
\phi_V := \mathbb{I}_{\{V_T \geq H\}} + \frac{V_T - H}{H} \mathbb{I}_{\{V_T < H\}}.
\] (3.17)

For \( \alpha \in (0, 1) \) we denote by \( \mathcal{V}^\alpha \) the set
\[
\mathcal{V}^\alpha := \{ \phi_V \in \mathcal{R} : V \in \mathcal{V}, \mathbb{E}_P[\phi_V] \geq \alpha \}.
\]

**Remark 3.7.** Note that for \( V \in \mathcal{V} \) we have that \( V_T \geq 0 \) \( P \)-a.s. In particular, \( P(\{H = 0\} \cap \{V_T < \)
\( \{ H \} = 0 \) and hence (3.17) is well-defined.

In the following, we formulate the optimization problem (3.1) in terms of success ratios and prove that it is equivalent to (3.9), see Proposition 3.8 below.

Consider the minimization problem

\[
\inf \left\{ \sup_{\mathbf{p} \in \mathcal{P}} \mathbb{E}^* [\varphi_V] : V \in \mathcal{V}^\alpha \right\}. \tag{3.18}
\]

**Proposition 3.8.** There exists an admissible strategy with value process \( \tilde{V} \) such that

\[
\mathbb{E}_P [\varphi_{\tilde{V}}] = \alpha,
\]

and

\[
\inf_{V \in \mathcal{V}^\alpha} \sup_{\mathbf{p} \in \mathcal{P}} \mathbb{E}^* [H \varphi_V] = \sup_{\mathbf{p} \in \mathcal{P}} \mathbb{E}^* [H \varphi_{\tilde{V}}], \tag{3.19}
\]

where \( \varphi_V \) denotes the success ratio associated to a portfolio \( V \in \mathcal{V} \) as in (3.17). Moreover, \( \varphi_{\tilde{V}} \) coincides with the solution \( \tilde{\varphi} \) from Proposition 3.5.

**Proof.** Note that

\[ \{ \varphi_V \in \mathcal{R} : V \in \mathcal{V}^\alpha \} \subseteq \mathcal{R}^\alpha, \]

and thus

\[
\inf_{\varphi \in \mathcal{R}^\alpha} \sup_{\mathbf{p} \in \mathcal{P}} \mathbb{E}^*[H \varphi] \leq \inf_{V \in \mathcal{V}^\alpha} \sup_{\mathbf{p} \in \mathcal{P}} \mathbb{E}^*[H \varphi_V]. \tag{3.20}
\]

By Proposition 3.5, we know that the left hand side of (3.20) admits a solution \( \tilde{\varphi} \in \mathcal{R} \). We prove that there exists \( \tilde{V} \in \mathcal{V}^\alpha \) such that

\[
\tilde{\varphi} = \varphi_{\tilde{V}} \quad \text{P-a.s.}
\]

Define the the modified claim

\[
\tilde{H} := H \tilde{\varphi}.
\]

By Theorem 7.13 of (Föllmer & Schied, 2016) there exists a minimal superhedging strategy \( \tilde{\xi} \).
with value process \( \tilde{V} \) for \( \tilde{H} \) such that

\[
\tilde{V}_0 = \sup_{P^* \in \mathcal{P}} \mathbb{E}^* \left[ \tilde{H} \right].
\]

First, \( \tilde{\xi} \) can be assumed to be admissible by Remark 3.1 and hence \( \tilde{V} \in \mathcal{V} \). Now, we show that \( \tilde{V} \in \mathcal{V}^* \). We have

\[
\varphi_{\tilde{V}} = \mathbb{1}_{\{\tilde{V}_T \geq H\}} + \frac{\tilde{V}_T}{H} \mathbb{1}_{\{\tilde{V}_T < H\}} \geq \hat{\varphi} \mathbb{1}_{\{\tilde{V}_T \geq H\}} + \frac{H \hat{\varphi}}{H} \mathbb{1}_{\{\tilde{V}_T < H\}} = \hat{\varphi}, \quad (3.21)
\]

where we used that \( \tilde{V} \) is the value process of the minimal superhedging strategy of \( \tilde{H} = H \hat{\varphi} \) and \( 0 \leq \hat{\varphi} \leq 1 \). Therefore, we get

\[
\mathbb{E}_P[\varphi_{\tilde{V}}] \geq \mathbb{E}_P[\hat{\varphi}] \geq \alpha,
\]

so \( \tilde{V} \in \mathcal{V}^* \) and \( \varphi_{\tilde{V}} \in \mathcal{R}^* \). It is left to show that \( \hat{\varphi} = \varphi_{\tilde{V}} \) \( P \)-a.s. By (3.21) we obtain \( \varphi_{\tilde{V}} \geq \hat{\varphi} \).

For the reverse direction we first show that \( \varphi_{\tilde{V}} \) is also a minimizer of the problem (3.10), i.e.,

\[
\sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H \varphi_{\tilde{V}}] \leq \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H \hat{\varphi}].
\]

Indeed, since \( \tilde{V} \) is the value process of an admissible strategy, \( V \) is a \( P^* \)-martingale for all \( P^* \in \mathcal{P} \) by Theorem 5.14 of (Föllmer & Schied, 2016) and thus we get that

\[
\sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H \varphi_{\tilde{V}}] = \sup_{P^* \in \mathcal{P}} \mathbb{E}^* \left[ H \left( \mathbb{1}_{\{\tilde{V}_T \geq H\}} + \frac{\tilde{V}_T}{H} \mathbb{1}_{\{\tilde{V}_T < H\}} \right) \right] \leq \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[\tilde{V}_T] = \tilde{V}_0 = \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H \hat{\varphi}], \quad (3.22)
\]

where we used in the last equality that \( \tilde{V}_0 \) is the superhedging price of \( \tilde{H} = H \hat{\varphi} \). In particular, \( \varphi_{\tilde{V}} \in \mathcal{R}^* \) is a minimizer. By the same arguments as in (3.16) it follows that

\[
\mathbb{E}_P[\varphi_{\tilde{V}}] = \alpha. \quad (3.23)
\]

Thus, we get by (3.16) and (3.23) that

\[
\mathbb{E}_P[\varphi_{\tilde{V}}] = \alpha = \mathbb{E}_P[\hat{\varphi}],
\]

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i.e., $E[\varphi_\hat{V} - \hat{\varphi}] = 0$. Together with (3.21), this implies $\varphi_\hat{V} = \hat{\varphi}$ $P$-a.s. We have proved that $\hat{V} \in \mathcal{V}^\alpha$ and
\[
\sup_{\mathcal{P} \in \mathcal{P}} E^* [H \varphi_{\hat{V}}] = \inf_{\varphi \in \mathcal{R}^n} \sup_{\mathcal{P} \in \mathcal{P}} E^* [H \varphi] \leq \inf_{V \in \mathcal{V}^\alpha} \sup_{\mathcal{P} \in \mathcal{P}} E^* [H \varphi_{V}].
\]
In particular, $\varphi_{\hat{V}}$ solves (3.19) and the quantile hedging formulations of (3.9) and (3.18) are equivalent.

**Corollary 3.9.** The following convergence holds:
\[
\inf_{V \in \mathcal{V}^\alpha} \sup_{\mathcal{P} \in \mathcal{P}} E^* [H \varphi_{\hat{V}}] \overset{\text{a.s.}}{\longrightarrow} \sup_{\mathcal{P} \in \mathcal{P}} E^* [H],
\]
where $\varphi_V$ denotes the success ratio associated to a portfolio $V \in \mathcal{V}$ as in (3.17).

**Proof.** The proof is similar to the one of Theorem 3.4 and is omitted.

### 3.2 Neural network approximation for $t = 0$

We now study how to approximate the superhedging price at $t = 0$ by using neural networks.

We recall the following definition, see e.g. (Buehler et al., 2019). Common choices for $\sigma$ below are $\sigma(x) = \frac{1}{1 + e^{-x}}$ and $\sigma(x) = \tanh(x)$.

In order to use the neural network approximation, we assume from now on that $\mathcal{F}_t = \sigma(Y_0, \ldots, Y_t)$ for $t = 0, \ldots, T$ and for some $\mathbb{R}^m$-valued process $Y = (Y_t)_{t=0,\ldots,T}$ for some $m \in \mathbb{N}$, and write $\mathcal{Y}_t = (Y_0, \ldots, Y_t)$ for $t \geq 0$.

**Definition 3.10.** Consider $L, N_0, N_1, \ldots, N_L \in \mathbb{N}$ with $L \geq 2$, $\sigma : (\mathbb{R}, \mathcal{B}(\mathbb{R})) \to (\mathbb{R}, \mathcal{B}(\mathbb{R}))$ measurable and for any $\ell = 1, \ldots, L$, let $W_\ell : \mathbb{R}^{N_{\ell-1}} \to \mathbb{R}^{N_\ell}$ be an affine function. A function $F : \mathbb{R}^{N_0} \to \mathbb{R}^{N_L}$ defined as
\[
F(x) = W_L \circ F_{L-1} \circ \cdots \circ F_1 \text{ with } F_\ell = \sigma \circ W_\ell \text{ for } \ell = 1, \ldots, L - 1,
\]
is called a *(feed forward) neural network*. Here the activation function $\sigma$ is applied component-wise. $L$ denotes the number of layers, $N_1, \ldots, N_{L-1}$ denote the dimensions of the hidden layers and $N_0, N_L$ the dimension of the input and output layers, respectively. For any $\ell = 1, \ldots, L$ the affine function $W_\ell$ is given as $W_\ell(x) = A_\ell^\ell x + b_\ell^\ell$ for some $A_\ell^\ell \in \mathbb{R}^{N_\ell \times N_{\ell-1}}$ and $b_\ell^\ell \in \mathbb{R}^{N_\ell}$.
For any $i = 1, \ldots N_\ell, j = 1, \ldots, N_\ell - 1$ the number $A^\ell_{ij}$ is interpreted as the weight of the edge connecting the node $i$ of layer $\ell - 1$ to node $j$ of layer $\ell$. The number of non-zero weights of a network is $\sum_{\ell=1}^L \|A^\ell\|_0 + \|b^\ell\|_0$, i.e. the sum of the number of non-zero entries of the matrices $A^\ell, \ell = 1, \ldots, L$, and vectors $b^\ell, \ell = 1, \ldots, L$.

For $k = 1, \ldots, T + 1$ we denote the set of all possible neural network parameters corresponding to neural networks mapping $\mathbb{R}^{m k} \to \mathbb{R}^d$ by

$$
\Theta_k = \bigcup_{L \geq 2} \bigcup_{(N_0, \ldots, N_L) \in \{mk\} \times N_\ell - 1 \times \{d\}} \left( \times_{\ell=1}^L \mathbb{R}^{N_\ell} \times \mathbb{R}^{N_{\ell-1}} \times \mathbb{R}^{N_1} \right).
$$

With $F^{\theta_k}$ we denote the neural network with parameters specified by $\theta_k \in \Theta_k$, see Definition 3.10. Recall that $F_t = \sigma(Y_0, \ldots, Y_t) = \sigma(Y_t)$ for $t = 0, \ldots, T$, and for some $\mathbb{R}^m$-valued stochastic process $Y$. Then, any $F_t$-measurable random variable $Z$ can be written as $Z = f_t(Y_t)$ for some measurable function $f_t$. Using Theorem B.1, $f_t$ can be approximated by a deep neural network in a suitable metric.

The approximate superhedging price is then

$$
\inf \mathcal{U}_0^{\Theta} = \inf \left\{ u \in \mathbb{R} : \exists \theta_k, \xi \in \Theta_k, k = 1, \ldots, T, \text{ s.t. } u + \sum_{k=1}^T F^{\theta_k, \xi}(Y_{k-1}) \cdot (X_k - X_{k-1}) \geq H \quad \text{P-a.s.} \right\}.
$$

(3.24)

For $\alpha \in (0, 1)$ the approximate $\alpha$-quantile hedging price is then

$$
\inf \mathcal{U}_0^{\Theta, \alpha} = \inf \left\{ u \in \mathbb{R} : \exists \theta_k, \xi \in \Theta_k, k = 1, \ldots, T \text{ s.t. } \mathbb{P} \left( u + \sum_{k=1}^T F^{\theta_k, \xi}(Y_{k-1}) \cdot (X_k - X_{k-1}) \geq H \right) \geq \alpha \right\}.
$$

(3.25)

For $C > 0$ we also define the truncated approximate superhedging price $\inf \mathcal{U}_0^{\Theta, C}$ and the truncated approximate $\alpha$-quantile hedging price $\inf \mathcal{U}_0^{\Theta, C, \alpha}$ with

$$
\mathcal{U}_0^{\Theta, C} := \left\{ u \in \mathbb{R} : \exists \theta_k, \xi \in \Theta_k, k = 1, \ldots, T \text{ s.t. } u + \sum_{k=1}^T (F^{\theta_k, \xi} \wedge C) \cdot (Y_{k-1}) \cdot (X_k - X_{k-1}) \geq H \quad \text{P-a.s.} \right\}
$$

(3.26)

and

$$
\mathcal{U}_0^{\Theta, C, \alpha} := \left\{ u \in \mathbb{R} : \exists \theta_k, \xi \in \Theta_k, k = 1, \ldots, T \text{ s.t. } \mathbb{P} \left( u + \sum_{k=1}^T (F^{\theta_k, \xi} \wedge C) \cdot (Y_{k-1}) \cdot (X_k - X_{k-1}) \geq H \right) \geq \alpha \right\},
$$

(3.27)
where the maximum and minimum are taken component-wise.
In the definitions of the (truncated) approximate superhedging price, in (3.24) and (3.26), and
of the (truncated) approximate $\alpha$-quantile hedging price, in (3.25) and (3.27), it cannot be
guaranteed that the trading strategies given by neural networks are admissible. For this reason
we need to impose Assumption 1 below.

**Assumption 1.** Suppose that

$$\inf \mathcal{U}_0 = \inf \mathcal{U}_0^{\text{bdd}} := \inf \left\{ u \in \mathbb{R} : \exists \xi \text{ pred. s.t. } \xi_k \in L^\infty \forall k \in \{1, \ldots, T\}, u + \sum_{k=1}^T \xi_k \cdot (X_k - X_{k-1}) \geq H \text{ P-a.s.} \right\}.$$  

**Remark 3.11.** Under Assumption 1 the superhedging price does not change if we restrict to
bounded strategies. This hypothesis is needed for the approximation result in Theorem 3.13,
as shown in Example 3.14. However, Assumption 1 is not very restrictive and holds in a wide
range of settings, for example in all models with a finite probability space, since in this case all
random variables are bounded. In particular, Assumption 1 is satisfied in any scenario-based
model as considered in the section on numerical results. Furthermore, Assumption 1 holds in the
case of $d = 1$ and bounded, independent price increments, i.e., if for each $t$ the price increment
$X_t - X_{t-1}$ is bounded and independent of $\mathcal{F}_{t-1}$ under $\mathbf{P}$, since in this case any admissible
strategy is necessarily bounded. This can be seen by contraposition. Let $t \in \{1, \ldots, T\}$ be the
first time at which $\xi$ is unbounded, i.e., $\mathbf{P}(\xi_t > n) > 0$ for all $n \in \mathbb{N}$ (the case $\mathbf{P}(\xi_t < -n) > 0$
for all $n \in \mathbb{N}$ can be treated analogously) and $\|\xi_k\|_\infty < \infty$ for $k < t$. Note that $\mathcal{P} \neq \emptyset$ and
for $\mathbf{P}^* \in \mathcal{P}$ the property $\mathbb{E}^*[X_t - X_{t-1}] = 0$ and $\mathbf{P} \approx \mathbf{P}^*$ imply that $\mathbf{P}(X_t - X_{t-1} \leq -C) > 0$
for some $C > 0$. Therefore, for $n \geq C^{-1} \sum_{k=0}^{t-1} \|\xi_k\|_\infty \|X_k - X_{k-1}\|_\infty$ it follows that $V_{t-1} \leq Cn$
$\mathbf{P}$-a.s. and

$$\mathbf{P}(V_t < 0) \geq \mathbf{P}(V_{t-1} \leq Cn, \xi_t(X_t - X_{t-1}) < -Cn) \geq \mathbf{P}(\xi_t > n)\mathbf{P}(X_t - X_{t-1} < -C) > 0.$$  

Hence, the strategy associated to $\xi$ can not be admissible.

Finally in a large class of models and for many commonly considered options the optimal
superhedging strategy is static, as shown in (Carassus et al., 2007). Consequently, Assumption 1
also holds in these settings.
Theorem 3.13 shows that \( \inf U_{0}^{\Theta, C, \alpha} \) can be used as an approximation of the superhedging price \( \inf U_{0} \). We start with a preliminary result.

For \( \alpha \in (0, 1] \), \( C > 0 \) define \( U_{0}^{C, \alpha} \) by

\[
U_{0}^{C, \alpha} := \left\{ u \in \mathbb{R} : \exists \xi \text{ pred. s.t. } \sup_{1 \leq k \leq T} \| \xi_k \|_{\infty} \leq C, \ P \left( u + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) \geq H \right) \geq \alpha \right\}.
\]

**Lemma 3.12.** Suppose Assumption 1 holds. Then for any \( \varepsilon > 0 \) there exists \( C \in (0, \infty) \) such that \( \lim_{\alpha \to 1} \inf U_{0}^{C, \alpha} \) exists and

\[
\inf U_{0}^{bd} \leq \lim_{\alpha \to 1} \inf U_{0}^{C, \alpha} \leq \inf U_{0}^{bd} + \varepsilon.
\]  
(3.28)

**Proof.** Let \( \varepsilon > 0 \) be fixed. Then there exists a predictable strategy \( \tilde{\xi} \) such that \( \sup_{1 \leq k \leq T} \| \tilde{\xi}_k \|_{\infty} < \infty \) and \( \inf U_{0}^{bd} + \frac{\varepsilon}{2} + \sum_{k=1}^{T} \tilde{\xi}_k \cdot (X_k - X_{k-1}) \geq H, \ P \)-a.s. Define \( C = C(\varepsilon) \) by

\[
C := \sup_{1 \leq k \leq T} \| \tilde{\xi}_k \|_{\infty} + 1.
\]  
(3.29)

Let \( (\alpha_n)_{n \in \mathbb{N}} \subset (0, 1) \) be a sequence such that \( \alpha_n \uparrow 1 \) as \( n \) tends to infinity. Then, \( \inf U_{0}^{C, \alpha_n} \leq \inf U_{0}^{C, \alpha_{n+1}} \leq \inf U_{0}^{C, 1} =: \inf U_{0}^{C} \) since

\[
U_{0}^{C, \alpha_n} \supset U_{0}^{C, \alpha_{n+1}},
\]

and therefore \( u_n \leq u_{n+1} \), where \( u_n := \inf U_{0}^{C, \alpha_n} \), for \( n \in \mathbb{N} \). Thus, the limit \( u^{C} = \lim_{n \to \infty} u_n \) is well-defined and \( u^{C} \leq \inf U_{0}^{C} \). Furthermore, for \( n \in \mathbb{N} \) and \( \delta > 0 \), there exists \( \xi^{(n)} \) predictable such that \( \sup_{1 \leq k \leq T} \| \xi^{(n)}_k \|_{\infty} \leq C \) and

\[
P \left( u_n + \delta + \sum_{k=1}^{T} \xi^{(n)}_k \cdot (X_k - X_{k-1}) \geq H \right) \geq \alpha_n.
\]  
(3.30)

For \( n \in \mathbb{N} \), define \( A_n \in \mathcal{F}_T \) by

\[
A_n := \left\{ u_n + \delta + \sum_{k=1}^{T} \xi^{(n)}_k \cdot (X_k - X_{k-1}) \geq H \right\}.
\]

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Then \( P(A_n) \geq \alpha_n \) and hence \( P(A_n) \uparrow 1 \) as \( n \) tends to infinity. Since \( \sup_{1 \leq k \leq T} \| \xi_k(n) \| \leq C \) for all \( n \in \mathbb{N} \) we get by Theorem 5.14 of (Föllmer & Schied, 2016) for any \( \mathbf{P}^* \in \mathcal{P} \) that

\[
 u_n + \delta = \mathbb{E}_{\mathbf{P}^*} \left[ u_n + \delta + \sum_{k=1}^T \xi_k^{(n)} \cdot (X_k - X_{k-1}) \right] \geq \mathbb{E}_{\mathbf{P}^*} \left[ H 1_{A_n} \right] + \mathbb{E}_{\mathbf{P}^*} \left[ \left( u_n + \delta + \sum_{k=1}^T \xi_k^{(n)} \cdot (X_k - X_{k-1}) \right) 1_{A_n^c} \right] \geq \mathbb{E}_{\mathbf{P}^*} \left[ H 1_{A_n} \right] + \mathbb{E}_{\mathbf{P}^*} \left[ \left( u_n + \delta - \sum_{k=1}^T \sum_{i=1}^d |\xi_k^{(n)}| |X_k^i - X_{k-1}^i| \right) 1_{A_n^c} \right] \geq \mathbb{E}_{\mathbf{P}^*} \left[ H 1_{A_n} \right] + \mathbb{E}_{\mathbf{P}^*} \left[ \left( u_n + \delta - C \sum_{k=1}^T \sum_{i=1}^d |X_k^i - X_{k-1}^i| \right) 1_{A_n^c} \right].
\]

(3.31)

Recall that \( X = (X^1, \ldots, X^d) \) is a \( d \)-dimensional \( \mathbf{P}^* \)-martingale, \( u_n \leq u^C \leq \inf U_0^{b, d} + \frac{\xi}{2}, n \in \mathbb{N} \) and thus for all \( n \in \mathbb{N} \)

\[
 |u_n + \delta - C \sum_{k=1}^T \sum_{i=1}^d |X_k^i - X_{k-1}^i| | \leq \left( |u^C + \delta| + |C| \sum_{k=1}^T \sum_{i=1}^d \|X_k^i - X_{k-1}^i\| \right) \in L^1(\Omega, \mathcal{F}_T, \mathbf{P}^*).
\]

Furthermore, \( 1_{A_n} \) converges to 1 in probability as \( n \) tends to infinity, since for any \( \gamma \in (0, 1) \) we have

\[
 P(\|1_{A_n} - 1\| > \gamma) = P(1_{A_n^c} > \gamma) = P(A_n^c) \xrightarrow{n \to \infty} 0,
\]

because of (3.30). By dominated convergence we obtain that

\[
 \lim_{n \to \infty} \mathbb{E}^* [H 1_{A_n}] = \mathbb{E}^*[H],
\]

and

\[
 \lim_{n \to \infty} \mathbb{E}^* \left[ \left( u_n + \delta - C \sum_{k=1}^T \sum_{i=1}^d |X_k^i - X_{k-1}^i| \right) 1_{A_n^c} \right] = 0.
\]

Note that for dominated convergence, it is sufficient that \( 1_{A_n} \) converges only in probability. Taking \( n \) to infinity in (3.31) and (3.32) yields

\[
 \lim_{n \to \infty} u_n + \delta = u^C + \delta \geq \lim_{n \to \infty} \left( \mathbb{E}^*[H 1_{A_n}] + \mathbb{E}^* \left[ \left( u_n + \delta - C \sum_{k=1}^T \sum_{i=1}^d |X_k^i - X_{k-1}^i| \right) 1_{A_n^c} \right] \right) = \mathbb{E}^*[H].
\]

(3.33)
As (3.33) holds for all \( P^* \in \mathcal{P} \) we get by the superhedging duality that
\[
\lim_{n \to \infty} \inf \mathcal{U}_0^{C,\alpha_n} + \delta = u^C + \delta \geq \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H] = \inf \mathcal{U}_0 = \inf \mathcal{U}_0^{bdd}.
\]
Because \( \delta > 0 \) was arbitrary, this implies
\[
\lim_{\alpha \to 1} \inf \mathcal{U}_0^{C,\alpha} \geq \inf \mathcal{U}_0 = \inf \mathcal{U}_0^{bdd}.
\]
To conclude the proof of (3.28), we note that \( (\inf \mathcal{U}_0^{bdd} + \frac{\varepsilon}{2}) \in \mathcal{U}_0^{C} \) by definition. This implies that
\[
\lim_{\alpha \to 1} \inf \mathcal{U}_0^{C,\alpha} \leq \inf \mathcal{U}_0^{C} \leq \inf \mathcal{U}_0^{bdd} + \varepsilon,
\]
hence (3.28) follows. \( \square \)

We can now prove the main result.

**Theorem 3.13.** Assume \( \sigma \) is bounded and non-constant. Further, suppose Assumption 1 is fulfilled. Then for any \( \varepsilon > 0 \) there exists \( \alpha_0 = \alpha_0(\varepsilon) \in (0,1) \) and \( C = C(\varepsilon) \in (0, \infty) \) such that for all \( \alpha \in (\alpha_0,1) \)
\[
\inf \mathcal{U}_0 + \varepsilon \geq \inf \mathcal{U}_0^{\Theta,C,\alpha} \geq \inf \mathcal{U}_0 - \varepsilon.
\]

**Proof.** By Assumption 1 we can consider \( \inf \mathcal{U}_0^{bdd} \) instead of \( \inf \mathcal{U}_0 \). Then for \( \varepsilon > 0 \) there exists a predictable strategy \( \tilde{\xi} \) such that \( \sup_{1 \leq k \leq T} \| \tilde{\xi}_k \|_\infty < \infty \) and \( \inf \mathcal{U}_0^{bdd} + \frac{\varepsilon}{2} + \sum_{k=1}^{T} \tilde{\xi}_k \cdot (X_k - X_{k-1}) \geq H, \) \( \mathbb{P} \)-a.s. Define \( C = C(\varepsilon) \) as in (3.29) in the proof of Lemma 3.12. Then we observe that \( \mathcal{U}_0^{\Theta,C,\alpha} \subset \mathcal{U}_0^{C,\alpha} \) for all \( \alpha \in (0,1) \) and (3.28) implies that there exists \( \alpha_0 = \alpha_0(\varepsilon) \in (0,1) \) such that for all \( \alpha \in (\alpha_0,1) \)
\[
\inf \mathcal{U}_0 - \varepsilon = \inf \mathcal{U}_0^{bdd} - \varepsilon \leq \inf \mathcal{U}_0^{C,\alpha} \leq \inf \mathcal{U}_0^{\Theta,C,\alpha},
\]
which proves the second inequality in (3.34).

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To prove the first inequality in (3.34), let \( \alpha \) be given. Consider

\[
M_n = \left\{ \inf \mathcal{U}_0^{\text{bdd}} + \frac{\varepsilon}{2} + \sum_{k=1}^{T} \hat{\xi}_k \cdot (X_k - X_{k-1}) \geq H \right\} \cap \{ \|X_k - X_{k-1}\| \leq n \text{ for } k = 1, \ldots, T \},
\]

for \( n \in \mathbb{N} \). Then \( M_n \subset M_{n+1} \) and therefore by continuity from below

\[
1 = \mathbf{P} \left( \inf \mathcal{U}_0^{\text{bdd}} + \frac{\varepsilon}{2} + \sum_{k=1}^{T} \hat{\xi}_k \cdot (X_k - X_{k-1}) \geq H \right) = \mathbf{P}(\cup_{n \in \mathbb{N}} M_n) = \lim_{n \to \infty} \mathbf{P}(M_n).
\]

Thus, we may choose \( n \in \mathbb{N} \) such that \( \mathbf{P}(M_n) \geq \frac{\alpha + 1}{2} \). As \( \hat{\xi} \) is predictable, for each \( k = 1, \ldots, T \) there exists a measurable function \( f_k: (\mathbb{R}^m, \mathcal{B}(\mathbb{R}^m)) \to (\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d)) \) such that \( \hat{\xi}_k = f_k(Y_{k-1}) \).

By the universal approximation theorem (Hornik, 1991, Theorem 1 and Section 3), see also Theorem B.1 in the appendix, with measure \( \mu \) given by the law of \( Y_{k-1} \) under \( \mathbf{P} \), for each \( k = 1, \ldots, T \) there exists \( \theta_{k, \hat{\xi}} \in \Theta \) such that

\[
\mathbf{P}(D_k) < \frac{1 - \alpha}{2T}, \quad \text{where } D_k = \left\{ \omega \in \Omega: \|f_k(Y_{k-1}(\omega)) - F^{\theta_{k, \hat{\xi}}, k}(Y_{k-1}(\omega))\| > \left( \frac{\varepsilon}{2nT} \wedge \frac{1}{2} \right) \right\}.
\]

Define

\[
\tilde{F}^{\theta_{k, \hat{\xi}}} := \left( F^{\theta_{k, \hat{\xi}}} \wedge C \right) \vee (-C), \quad k = 1, \ldots, T.
\]

By the definition of \( C \) in (3.29), we get that

\[
\|\hat{\xi}_k\|_\infty + \left( \frac{\varepsilon}{2nT} \wedge \frac{1}{2} \right) < C \quad \text{for all } k = 1, \ldots, T.
\]

On \( D_k^c \) we have for \( i \in \{1, \ldots, d\} \) that

\[
\left| F_i^{\theta_{k, \hat{\xi}}}(Y_{k-1}) \right| \leq \left| F_i^{\theta_{k, \hat{\xi}}}(Y_{k-1}) \right| \leq \|\hat{\xi}_k\|_\infty + \left( \frac{\varepsilon}{2nT} \wedge \frac{1}{2} \right) < C,
\]

and hence \( \tilde{F}_i^{\theta_{k, \hat{\xi}}}(Y_{k-1}) = F_i^{\theta_{k, \hat{\xi}}}(Y_{k-1}) \) on \( D_k^c \). Conversely, for \( \omega \in \Omega \) such that

\[
\|f_k(Y_{k-1}(\omega)) - F^{\theta_{k, \hat{\xi}}, k}(Y_{k-1}(\omega))\| \leq \left( \frac{\varepsilon}{2nT} \wedge \frac{1}{2} \right),
\]

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we get for \(i \in \{1, \ldots, d\}\) that
\[
\left| \tilde{F}_{\theta, \xi}^k(Y_{k-1}(\omega)) \right| \leq \left\| \tilde{F}_{\theta, \xi}^k(Y_{k-1}(\omega)) \right\| \leq \left\| \tilde{\xi}_k \right\|_\infty + \left( \frac{\varepsilon}{2nT} \wedge \frac{1}{2} \right) < C,
\]
and hence \(\bar{F}_{\theta, \xi}^k(Y_{k-1}(\omega)) = F_{\theta, \xi}^k(Y_{k-1}(\omega))\). In particular,
\[
\left\{ \omega \in \Omega : \|f_k(Y_{k-1}(\omega)) - F_{\theta, \xi}^k(Y_{k-1}(\omega))\| \leq \left( \frac{\varepsilon}{2nT} \wedge \frac{1}{2} \right) \right\} = \left\{ \omega \in \Omega : \|f_k(Y_{k-1}(\omega)) - F_{\theta, \xi}^k(Y_{k-1}(\omega))\| \leq \left( \frac{\varepsilon}{2nT} \wedge \frac{1}{2} \right) \right\},
\]
for all \(k = 1, \ldots, T\). Therefore, we get that \(D_k = \bar{D}_k\) with
\[
\bar{D}_k = \left\{ \omega \in \Omega : \|f_k(Y_{k-1}(\omega)) - \bar{F}_{\theta, \xi}^k(Y_{k-1}(\omega))\| > \left( \frac{\varepsilon}{2nT} \wedge \frac{1}{2} \right) \right\},
\]
and
\[
P(\bar{D}_k) < \frac{1 - \alpha}{2T}.
\]
On \(M_n \cap \bar{D}_1 \cap \ldots \cap \bar{D}_T\) we have
\[
\sum_{k=1}^T \tilde{\xi}_k \cdot (X_k - X_{k-1}) = \sum_{k=1}^T (\tilde{\xi}_k - \bar{F}_{\theta, \xi}^k(Y_{k-1})) \cdot (X_k - X_{k-1}) + \sum_{k=1}^T \bar{F}_{\theta, \xi}^k(Y_{k-1}) \cdot (X_k - X_{k-1})
\]
\[
\leq \sum_{k=1}^T \|f_k(Y_{k-1}) - \bar{F}_{\theta, \xi}^k(Y_{k-1})\| \|X_k - X_{k-1}\| + \sum_{k=1}^T \bar{F}_{\theta, \xi}^k(Y_{k-1}) \cdot (X_k - X_{k-1})
\]
\[
\leq \frac{\varepsilon}{2} + \sum_{k=1}^T \bar{F}_{\theta, \xi}^k(Y_{k-1}) \cdot (X_k - X_{k-1})
\]
and therefore
\[
M_n \cap \bar{D}_1 \cap \ldots \cap \bar{D}_T \subset \left\{ \inf U_0^{\text{bd}} + \varepsilon + \sum_{k=1}^T \bar{F}_{\theta, \xi}^k(Y_{k-1}) \cdot (X_k - X_{k-1}) \geq H \right\}.
\]
This inclusion and the Fréchet inequalities yield
\[
P \left( \inf U_0^{\text{add}} + \varepsilon + \sum_{k=1}^{T} \tilde{F}_{\theta_k, \tilde{\xi}}(Y_{k-1}) \cdot (X_k - X_{k-1}) \geq H \right)
\geq P(M_n \cap \tilde{D}_1 \cap \ldots \cap \tilde{D}_T)
\geq P(M_n) + P(\tilde{D}_1^c) + \cdots + P(\tilde{D}_T^c) - T \geq \frac{\alpha + 1}{2} + T \left( 1 - \frac{1 - \alpha}{2T} \right) - T = \alpha.
\]
This proves the left inequality of (3.34). □

We now provide a counterexample, which shows that Assumption 1 is necessary for (3.34) to hold. In particular, this implies that the approximation result in Theorem 3.13 cannot be applied without Assumption 1.

Example 3.14. Let \( Z_1, Z_2 \) be independent standard uniform random variables under \( P \) and let \( \Phi \) be the standard normal cumulative distribution function. Consider the market model with \( T = 2, d = 1, S_t^0 = 1 \) for \( t \in \{0, 1, 2\}, X_0 = 1, X_1 = Z_1 + 0.5, X_2 = X_1 + (Z_2 - 0.5)/(1 + |\Phi^{-1}(Z_1)|) \) and \( Y = X \). Then \( P \in \mathcal{P} \) and \( H = 1 + \Phi^{-1}(Z_1)(X_2 - X_1) \) is a bounded contingent claim, since \( |\Phi^{-1}(Z_1)(X_2 - X_1)| \leq |Z_2 - 0.5| < 1 \). The self-financing strategy induced by the predictable process \( \xi^* \) with \( \xi_1^* = 0, \xi_2^* = \Phi^{-1}(Z_1) \) and initial wealth 1 is a replicating strategy for \( H \), hence \( \inf U_0 = 1 \). On the other hand, let \( v > 0 \) and consider \( \xi \) predictable and bounded. If \( V_T = v + \sum_{k=1}^{T} \xi_k(X_k - X_{k-1}) \) super-replicates \( H \), then
\[
(1 + |\Phi^{-1}(Z_1)|)\xi_1(Z_1 - 0.5) + \xi_2(Z_2 - 0.5) + v - 1 \geq |\Phi^{-1}(Z_1)|[1 - v + (Z_2 - 0.5)\text{sign}(\Phi^{-1}(Z_1))].
\]
(3.37)
If \( \xi_1 > 0 \), then the left hand side is negative on the event \( \{ Z_1 < \frac{1}{R} \} \) for \( R > 0 \) large enough, since \( \xi_2 \) is bounded. Thus, for \( R > 0 \) large enough, on the event \( \{ Z_1 < \frac{1}{R} \} \cap \{ 0.3 \leq Z_2 \leq 0.4 \} \) the left hand side of (3.37) is negative, whereas the right hand side is non-negative for \( v < 1.1 \). This means that necessarily \( v \geq 1.1 \), otherwise \( V_T \geq H \) can not be satisfied \( P \text{-a.s.} \). In the case \( \xi_1 < 0 \) the same conclusion can be made using the set \( \{ Z_1 > 1 - \frac{1}{R} \} \cap \{ 0.6 \leq Z_2 \leq 0.7 \} \). This proves that \( \inf U_0^{\text{add}} \geq 1.1 > \inf U_0 \), i.e., Assumption 1 is not satisfied.

We now argue that in this example the first inequality in (3.34) does not hold, i.e., for all \( \alpha_0 \in (0, 1), C > 0 \) there exists \( \alpha \geq \alpha_0 \) such that \( \inf U_0^{\Phi, C, \alpha} > \inf U_0 + 0.05 \). To prove this, let \( v > 0 \) and
\( \xi \) predictable satisfy \( \sup_{1 \leq k \leq T} \| \xi_k \| \leq C \) and \( P \left( v + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) \geq H \right) \geq \alpha_0 \). The super-replication condition can again be rewritten as (3.37) and same reasoning as above shows that there exists \( R > 0 \) such that for all \( v < 1.1 \) we have \( P \left( v + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) \geq H \right) \leq 1 - \frac{1}{10R} \), since \( P(\{Z_1 < \frac{1}{R}\} \cap \{0.3 \leq Z_2 \leq 0.4\}) = P(\{Z_1 > 1 - \frac{1}{R}\} \cap \{0.6 \leq Z_2 \leq 0.7\}) = \frac{1}{10R} \).

Thus, for all \( \alpha > 1 - \frac{1}{10R} \) it follows that \( \inf \mathcal{U}_0^{C,\alpha} \geq 1.1 \). The inclusion \( \mathcal{U}_0^{\Theta,\alpha} \subset \mathcal{U}_0^{C,\alpha} \) then implies \( \inf \mathcal{U}_0^{\Theta,\alpha} \geq \inf \mathcal{U}_0^{C,\alpha} \geq 1.1 > \inf \mathcal{U}_0 + 0.05 \).

**Remark 3.15.** Note that in the proof of Theorem 3.13 we compute both the price at \( t = 0 \) and the superhedging strategy for the complete interval.

**Remark 3.16.** Thanks to the universal approximation theorem in (Hornik, 1991), we could in fact restrict our attention to neural networks with one hidden layer and the result in Theorem 3.13 remains valid. Thus, for each \( k = 1, \ldots, T \) we could fix \( L = 2, N_0 = mk, N_2 = d \) and consider instead the simpler parameter sets

\[
\Theta_k = \bigcup_{N_1 \in \mathbb{N}} (\mathbb{R}^{N_1 \times mk} \times \mathbb{R}^{N_1}) \times (\mathbb{R}^{d \times N_1} \times \mathbb{R}^d)
\]

\[
\Theta_k^C = ([-C, C]^{d \times N_1} \times [-C, C]^d) \times ([-C, C]^{d \times N_1} \times [-C, C]^d).
\]

Note the simpler form of \( \Theta_k^C \), which is due to the fact that all one-hidden layer networks with 
\( N_1 \leq C \) hidden nodes can be written as one-hidden layer networks with \( C \) hidden nodes and appropriate weights set to 0.

## 4 Superhedging price for \( t > 0 \)

In this section we establish a method to approximate superhedging prices for \( t > 0 \). Using a version of the uniform Doob decomposition, see Theorem 7.5 of (Föllmer & Schied, 2016), the problem reduces to the approximation of the so-called process of consumption. In the first part, we build the theoretical basis for this approach. In the second part we prove that this method can be used to approximate the superhedging price for \( t > 0 \) by neural networks.
4.1 Uniform Doob Decomposition

We briefly summarize some results on superhedging in discrete time in Corollary 2.3 below. For a more detailed overview we refer to Chapter 7 of (Föllmer & Schied, 2016).

Recall that $H$ denotes a discounted European claim satisfying

$$
\sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H] < \infty.
$$

The superhedging price at $t = 0$, $\sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H]$ and the associated strategy $\xi$ can be calculated as in Section 3 and so we consider them as known. The remaining unknown component is the process of consumption $B$ given by (2.2). By Corollary 2.3,

$$
\left( \esssup_{P^* \in \mathcal{P}} \mathbb{E}^*[H \mid \mathcal{F}_t] \right)_{t=0,1,\ldots,T}
$$

is the smallest $\mathcal{P}$-supermartingale whose terminal value dominates $H$. Consider the stochastic process $\tilde{B} = (\tilde{B}_t)_{t=0,\ldots,T}$ defined as $\tilde{B}_0 := 0$ and for $t = 1, \ldots, T$,

$$
\tilde{B}_t := \esssup B_t,
$$

where

$$
B_t := \left\{ D_t \in L^0(\Omega, \mathcal{F}_t, P) : \tilde{B}_{t-1} \leq D_t \leq \sup_{P^* \in \mathcal{P}} \mathbb{E}^*[H] + \sum_{k=1}^T \xi_k \cdot (X_k - X_{k-1}) - H \text{ P-a.s.} \right\}.
$$

**Proposition 4.1.** We have that

$$
B_t = \tilde{B}_t \quad \text{P-a.s., for all } t = 0, \ldots, T,
$$

where $B$ is given in (2.2) and $\tilde{B}$ in (4.1), respectively.

**Proof.** The proof follows by induction. For $t = 0$ we have $B_0 = 0 = \tilde{B}_0$ by definition. For the induction step assume that $B_{t-1} = \tilde{B}_{t-1}$ P-a.s. for some $1 \leq t \leq T$. First we observe that $B_t \geq \tilde{B}_{t-1}$ because $B$ is increasing and by the assumption of the induction step. In addition,
by (2.4) we obtain
\[
\sup_{P^* \in \mathcal{P}} E^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \geq B_t.
\] (4.3)

In particular, \( B_t \in \mathcal{B}_t \) and thus \( B_t \leq \tilde{B}_t \) \( \mathbb{P} \)-a.s. Define \( \tilde{V} = (\tilde{V}_s)_{s=0,\ldots,T} \) by
\[
\tilde{V}_s := \sup_{P^* \in \mathcal{P}} E^*[H] + \sum_{k=1}^{s} \xi_k \cdot (X_k - X_{k-1}) - \tilde{B}_s
\]

First, we note that
\[
\sup_{P^* \in \mathcal{P}} E^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) \geq H \geq 0 \quad \mathbb{P}\text{-a.s.}
\]

and thus by Theorem 5.14 of (Föllmer & Schied, 2016) we have that
\[
\left( \sup_{P^* \in \mathcal{P}} E^*[H] + \sum_{k=1}^{s} \xi_k \cdot (X_k - X_{k-1}) \right)_{s=0,\ldots,T}
\]
is a \( \tilde{P}^* \)-martingale for all \( \tilde{P}^* \in \mathcal{P} \). Further, by (4.1) and (4.2) we obtain
\[
0 \leq \tilde{B}_s \leq \sup_{P^* \in \mathcal{P}} E^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \quad \text{for all } s = 0,\ldots,T, \mathbb{P}\text{-a.s.}
\]

and
\[
\sup_{P^* \in \mathcal{P}} E^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \in L^1(\Omega, \mathcal{F}, \tilde{P}^*) \quad \text{for all } \tilde{P}^* \in \mathcal{P},
\]
implies that \( \tilde{V}_s \in L^1(\Omega, \mathcal{F}_s, \mathbb{P}^*) \) for all \( \mathbb{P}^* \in \mathcal{P} \) and all \( s = 0,\ldots,T \). In particular, since \( \tilde{B} \) is increasing and non-negative, we can conclude that \( \tilde{V} \) is a \( \mathbb{P}^* \)-supermartingale for all \( \mathbb{P}^* \in \mathcal{P} \). Furthermore, \( \tilde{V}_s \geq 0 \) \( \mathbb{P} \)-a.s. for all \( s = 0,\ldots,T \). To this end, let \( \mathbb{P}^* \in \mathcal{P} \) be arbitrary, then we have by the \( \mathbb{P}^* \)-supermartingale property that
\[
\tilde{V}_s \geq E^*[\tilde{V}_T | \mathcal{F}_s]
= E^* \left[ \sup_{P^* \in \mathcal{P}} E_{P^*}[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - \tilde{B}_T | \mathcal{F}_s \right]
\geq E^*[H | \mathcal{F}_s] \geq 0.
\]
The terminal value of $\tilde{V}$ dominates $H$ by construction and since $B_s \leq \tilde{B}_s$ for all $s = 0, \ldots, T$, we have

$$\tilde{V}_s \leq \text{ess sup}_{\mathbf{P}^* \in \mathcal{P}} \mathbb{E}^*[H | \mathcal{F}_s] \quad \mathbf{P}\text{-a.s. for all } s = 0, 1, \ldots, T.$$ 

Therefore, we get

$$\tilde{V}_s = \text{ess sup}_{\mathbf{P}^* \in \mathcal{P}} \mathbb{E}^*[H | \mathcal{F}_s] = \sup_{\mathbf{P}^* \in \mathcal{P}} \mathbb{E}^*[H] + \sum_{k=1}^{s} \xi_k \cdot (X_k - X_{k-1}) - B_s \quad \mathbf{P}\text{-a.s. for all } s = 0, 1, \ldots, T,$$

and thus $B_t = \tilde{B}_t \mathbf{P}\text{-a.s. This concludes the proof.}$

**Remark 4.2.** In the definition of (4.1) we can equivalently consider $\text{ess sup} \tilde{B}_t$, where

$$\tilde{B}_t := \left\{ D_t \in L^0(\Omega, \mathcal{F}_t, \mathbf{P}) : 0 \leq D_t \leq \sup_{\mathbf{P}^* \in \mathcal{P}} \mathbb{E}^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \right\}$$

for $t = 1, \ldots, T$. This is due to the fact that, on the one hand $B_t \subset \tilde{B}_t$ for all $t = 1, \ldots, T$. On the other hand, for $D_t \in \tilde{B}_t$ we have that $\tilde{D}_t := D_t \vee B_{t-1} \in \mathcal{B}_t$ and $D_t \leq \tilde{D}_t \mathbf{P}\text{-a.s. Therefore, } \text{ess sup} \tilde{B}_t = \text{ess sup} B_t = B_t$ for all $t = 1, \ldots, T$.

### 4.2 Neural network approximation for $t > 0$

We now study a neural network approximation for the superhedging price process for $t > 0$. Throughout this section we use the notation of Section 3. For $\varepsilon, \tilde{\varepsilon} \in (0, 1)$ we define the set

$$\mathcal{E}^0_{\varepsilon, \tilde{\varepsilon}} := \left\{ F^\theta_t(\mathcal{Y}_t) : \theta_t \in \mathcal{O}_{t+1} \text{ and } \mathbf{P} \left( B_{t-1} - \tilde{\varepsilon} \leq F^\theta_t(\mathcal{Y}_t) \leq \sup_{\mathbf{P}^* \in \mathcal{P}} \mathbb{E}^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H + \tilde{\varepsilon} \right) > 1 - \varepsilon \right\},$$

where $B$ is the consumption process for $H$ introduced in (2.2). We now construct an approximation of $B$ by neural networks.

**Proposition 4.3.** Assume $\sigma$ is bounded and non-constant. Then for any $\varepsilon, \tilde{\varepsilon} > 0$ there exist
neural networks \((F_{\theta_0,\epsilon,\tilde{\epsilon}}, \ldots, F_{\theta_T,\epsilon,\tilde{\epsilon}})\) such that \(F_{\theta_t,\epsilon,\tilde{\epsilon}}(Y_t) \in B_{\theta_t}^{\epsilon,\tilde{\epsilon}}\) for all \(t = 0, \ldots, T\) and

\[
\mathbb{P}( |F_{\theta_t,\epsilon,\tilde{\epsilon}}(Y_t) - B_t| > \tilde{\epsilon} ) < \epsilon, \quad \text{for all } t = 0, \ldots, T.
\]

In particular, there exists a sequence of neural networks \((F_{\theta_0}^{\ast}, \ldots, F_{\theta_T}^{\ast})_{n \in \mathbb{N}}\) with \(F_{\theta_t}^{\ast}(Y_t) \in B_{\theta_t}^{\epsilon,\tilde{\epsilon}}\) for all \(n \in \mathbb{N}\) and for all \(t = 0, \ldots, T\) such that

\[
(F_{\theta_0}^{\ast}(Y_0), \ldots, F_{\theta_T}^{\ast}(Y_T)) \xrightarrow{P.a.s.} (B_0, \ldots, B_T) \quad \text{for } n \to \infty.
\]

**Proof.** Fix \(\epsilon, \tilde{\epsilon} > 0\) and \(t \in \{1, \ldots, T\}\). Note that \(B_0 = 0\) by definition. Let \(B\) be given by the representation (4.1). Observe that the set \(B_t\) from (4.2) is directed upwards. By Theorem A.33 of (Föllmer & Schied, 2016) there exists an increasing sequence

\[
(B^k_t)_{k \in \mathbb{N}} \subset B_t,
\]

such that \(B^k_t\) converges \(P\)-almost surely to \(\bar{B}_t = B_t\) as \(k\) tends to infinity. Since almost sure convergence implies convergence in probability, there exists \(K = K(\epsilon, \tilde{\epsilon}) \in \mathbb{N}\) such that

\[
\mathbb{P}\left( |B^k_t - B_t| > \frac{\tilde{\epsilon}}{2} \right) < \frac{\epsilon}{2}, \quad \text{for all } k \geq K.
\]

(4.4)

For all \(k \geq K\) there exist measurable functions \(f^k_t : \mathbb{R}^{m_t} \to \mathbb{R}\) such that \(B^k_t = f^k_t(Y_t)\). Fix \(k \geq K\). By the universal approximation theorem (Hornik, 1991, Theorem 1 and Section 3), see also Theorem B.1 in the appendix, (with measure \(\mu\) given by the law of \(Y_t\) under \(P\)) there exists \(\theta_t = \theta^k_t \in \Theta_{t+1}\) and \(F_{\theta_t} = F_{\theta^k_t,\epsilon,\tilde{\epsilon}}\) such that

\[
\mathbb{P}\left( |f^k_t(Y_t) - F_{\theta_t}(Y_t)| > \frac{\tilde{\epsilon}}{2} \right) < \frac{\epsilon}{2}.
\]

By the triangle inequality and by De Morgan’s law we obtain that

\[
\{ \omega \in \Omega : |B_t(\omega) - F_{\theta_t}(Y_t(\omega))| > \tilde{\epsilon} \} \subseteq \{ \omega \in \Omega : |B_t(\omega) - B^k_t(\omega)| + |B^k_t - F_{\theta_t}(Y_t(\omega))| > \tilde{\epsilon} \}
\]

\[
\subseteq \left\{ \omega \in \Omega : |B_t(\omega) - B^k_t(\omega)| > \frac{\tilde{\epsilon}}{2} \right\} \cup \left\{ \omega \in \Omega : |B^k_t(\omega) - F_{\theta_t}(Y_t(\omega))| > \frac{\tilde{\epsilon}}{2} \right\}.
\]

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In particular, we obtain by sub-additivity that
\[ P \left( |B_t - F^{\theta_t}(Y_t)| > \hat{\varepsilon} \right) \leq P \left( |B_t - B^{\theta_t}| > \frac{\hat{\varepsilon}}{2} \right) + P \left( |B^{\theta_t} - F^{\theta_t}(Y_t)| > \frac{\hat{\varepsilon}}{2} \right) < \frac{\varepsilon}{2} + \frac{\varepsilon}{2} = \varepsilon. \]

Next, we show that \( F^{\theta_t} \in B^{\theta_t, \varepsilon, \hat{\varepsilon}} \). For this purpose, we note that
\[ B_{t-1} \leq B_t \leq \sup_{P \in \mathcal{P}} \mathbb{E}[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \quad \text{P-a.s.} \]

Therefore, we have that
\[ P \left( B_{t-1} - \hat{\varepsilon} \leq F^{\theta_t}(Y_t) \leq \sup_{P \in \mathcal{P}} \mathbb{E}[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H + \hat{\varepsilon} \right) \geq P \left( |B_t - F^{\theta_t}(Y_t)| \leq \hat{\varepsilon} \right) > 1 - \varepsilon, \]

which implies that \( F^{\theta_t}(Y_t) = F^{\theta_t, \varepsilon, \hat{\varepsilon}}(Y_t) \in B^{\theta_t, \varepsilon, \hat{\varepsilon}} \). We set \( \varepsilon = \frac{1}{n} = \hat{\varepsilon} \) for \( n \in \mathbb{N} \) and consider the neural network
\[
F^{\theta_t}_n := F^{\theta_t, K(n)} = \frac{1}{n}, \quad t \in \{1, \ldots, T\}, \quad n \in \mathbb{N},
\]
where \( K(n) = K(\frac{1}{n}, \frac{1}{n}) \) is given by (4.4). Then, \( F^{\theta_t}_n \in B^{\theta_t, \frac{1}{n}, \frac{1}{n}} \) for all \( n \in \mathbb{N} \) and for all \( t = 1, \ldots, T \). Further, we have
\[ P \left( \left| F^{\theta_t}_n(Y_t) - B_t \right| > \frac{1}{n} \right) < \frac{1}{n} \quad \text{for all } t = 1, \ldots, T, \]

which implies convergence in probability, i.e.,
\[ F^{\theta_t}_n(Y_t) \xrightarrow{P} B_t \quad \text{for } n \to \infty, \quad \text{for all } t = 0, \ldots, T. \]

By passing to a suitable subsequence, convergence also holds \( P \text{-a.s.} \) simultaneously for all \( t = 0, \ldots, T \). \( \square \)
Let \( \tilde{\varepsilon} > 0 \). Recursively, we define the set
\[
B^{\theta^*, \tilde{\varepsilon}}_t := \{ F^{\theta_t}(Y_t) 1_A + B^{\theta_{t-1}^*, \varepsilon}_{t-1} 1_{A^c} : \theta_t \in \Theta_{t+1}, A \in \mathcal{F}_t, \}
\]
\[
B^{\theta_{t-1}^*, \varepsilon}_{t-1} \leq F^{\theta_t}(Y_t) 1_A + B^{\theta_{t-1}^*, \varepsilon}_{t-1} 1_{A^c} \leq \sup_{\mathcal{P}^* \in \mathcal{P}} \mathbb{E}^*[H] + \sum_{k=1}^T \xi_k \cdot (X_k - X_{k-1}) - H + \tilde{\varepsilon}
\]
for \( t = 1, \ldots, T \), and the approximated process of consumption by \( B^{\theta^*, \tilde{\varepsilon}}_0 = 0 \) and
\[
B^{\theta^*, \tilde{\varepsilon}}_t := \operatorname{ess sup} B^{\theta^*, \tilde{\varepsilon}}_t \quad \text{for } t = 1, \ldots, T.
\]

**Theorem 4.4.** Assume \( \sigma \) is bounded and non-constant. Then
\[
\left| B^{\theta^*, \tilde{\varepsilon}}_t - B_t \right| \leq \tilde{\varepsilon} \quad \mathbb{P}\text{-a.s. for all } t = 0, \ldots, T.
\]

**Proof.** We prove the statement by induction. For \( t = 0 \) we have by definition \( B^{\theta^*, \tilde{\varepsilon}}_0 = B_0 = 0 \).
Assume now that
\[
\left| B^{\theta^*, \tilde{\varepsilon}}_{t-1} - B_{t-1} \right| \leq \tilde{\varepsilon} \quad \mathbb{P}\text{-a.s.}
\]
for some \( t \in \{1, \ldots, T\} \). First we note that \( B^{\theta^*, \tilde{\varepsilon}}_s \leq B^{\theta^*, \tilde{\varepsilon}}_{s+1} \) by (4.5) and (4.6), and because \( B^{\theta^*, \tilde{\varepsilon}}_0 = 0 \) it follows that \( B^{\theta^*, \tilde{\varepsilon}}_s \geq 0 \) for all \( s = 1, \ldots, T \). Let \( \theta_t \in \Theta_{t+1} \) and \( A \in \mathcal{F}_t \) such that
\[
0 \leq B^{\theta^*, \tilde{\varepsilon}}_{t-1} \leq F^{\theta_t}(Y_t) 1_A + B^{\theta_{t-1}^*, \varepsilon}_{t-1} 1_{A^c} \leq \sup_{\mathcal{P}^* \in \mathcal{P}} \mathbb{E}^*[H] + \sum_{k=1}^T \xi_k \cdot (X_k - X_{k-1}) - H + \tilde{\varepsilon}.
\]
Then, we can easily see that
\[
F^{\theta_t}(Y_t) 1_A + B^{\theta_{t-1}^*, \varepsilon}_{t-1} 1_{A^c} \in \left\{ D_t \in L^0(\Omega, \mathcal{F}_t, \mathbb{P}) : 0 \leq D_t \leq \sup_{\mathcal{P}^* \in \mathcal{P}} \mathbb{E}^*[H] + \sum_{k=1}^T \xi_k \cdot (X_k - X_{k-1}) - H + \tilde{\varepsilon} \mathbb{P}\text{-a.s.} \right\}.
\]
We now prove that
\[
B_t + \tilde{\varepsilon} = \operatorname{ess sup} \left\{ D_t \in L^0(\Omega, \mathcal{F}_t, \mathbb{P}) : -\tilde{\varepsilon} \leq D_t - \tilde{\varepsilon} \leq \sup_{\mathcal{P}^* \in \mathcal{P}} \mathbb{E}^*[H] + \sum_{k=1}^T \xi_k \cdot (X_k - X_{k-1}) - H \mathbb{P}\text{-a.s.} \right\}.
\]
(4.7)
On the one hand we have

\[
\begin{align*}
\{ D_t \in L^0(\Omega, \mathcal{F}_t, \mathbb{P}) : 0 \leq \hat{D}_t \leq \sup_{\mathbb{P}^* \in \mathbb{P}} \mathbb{E}^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \ P\text{-a.s.} \} &+ \hat{\epsilon} \\
= \{ D_t \in L^0(\Omega, \mathcal{F}_t, \mathbb{P}) : 0 \leq D_t - \hat{\epsilon} \leq \sup_{\mathbb{P}^* \in \mathbb{P}} \mathbb{E}^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \ P\text{-a.s.} \} \\
\subseteq \{ D_t \in L^0(\Omega, \mathcal{F}_t, \mathbb{P}) : -\hat{\epsilon} \leq D_t - \hat{\epsilon} \leq \sup_{\mathbb{P}^* \in \mathbb{P}} \mathbb{E}^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \ P\text{-a.s.} \},
\end{align*}
\]

which by Remark 4.2 implies that

\[
B_t + \hat{\epsilon} \leq \operatorname{ess\,sup} \{ D_t \in L^0(\Omega, \mathcal{F}_t, \mathbb{P}) : -\hat{\epsilon} \leq D_t - \hat{\epsilon} \leq \sup_{\mathbb{P}^* \in \mathbb{P}} \mathbb{E}^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \ P\text{-a.s.} \}.
\]

On the other hand, let

\[
D_t \subseteq \{ D_t \in L^0(\Omega, \mathcal{F}_t, \mathbb{P}) : -\hat{\epsilon} \leq D_t - \hat{\epsilon} \leq \sup_{\mathbb{P}^* \in \mathbb{P}} \mathbb{E}^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \ P\text{-a.s.} \},
\]

and define \( \hat{D}_t := D_t \vee \hat{\epsilon} \). Then \( D_t \leq \hat{D}_t \ P\text{-a.s.} \) and

\[
\hat{D}_t \subseteq \{ \hat{D}_t \in L^0(\Omega, \mathcal{F}_t, \mathbb{P}) : 0 \leq \hat{D}_t - \hat{\epsilon} \leq \sup_{\mathbb{P}^* \in \mathbb{P}} \mathbb{E}^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \ P\text{-a.s.} \},
\]

which implies that

\[
B_t + \hat{\epsilon} \geq \operatorname{ess\,sup} \{ D_t \in L^0(\Omega, \mathcal{F}_t, \mathbb{P}) : -\hat{\epsilon} \leq D_t - \hat{\epsilon} \leq \sup_{\mathbb{P}^* \in \mathbb{P}} \mathbb{E}^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \ P\text{-a.s.} \},
\]

and hence (4.7) follows. Further, we also have that

\[
\begin{align*}
\{ D_t \in L^0(\Omega, \mathcal{F}_t, \mathbb{P}) : 0 \leq D_t \leq \sup_{\mathbb{P}^* \in \mathbb{P}} \mathbb{E}^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H + \hat{\epsilon} \ P\text{-a.s.} \} \\
= \{ D_t \in L^0(\Omega, \mathcal{F}_t, \mathbb{P}) : -\hat{\epsilon} \leq D_t - \hat{\epsilon} \leq \sup_{\mathbb{P}^* \in \mathbb{P}} \mathbb{E}^*[H] + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) - H \ P\text{-a.s.} \}.
\end{align*}
\]
Therefore, we obtain by (4.7) that
\[ F^\theta_t(Y_t)1_{A} + B^\theta_{t-1} \tilde{\varepsilon} 1_{A^c} \leq B_t + \tilde{\varepsilon} \quad \text{P-a.s.}, \]
and hence
\[ B^\theta_{t} \tilde{\varepsilon} \leq B_t + \tilde{\varepsilon} \quad \text{P-a.s.} \tag{4.8} \]
For the converse direction let \( \varepsilon \in (0, 1) \). By the proof of Proposition 4.3 there exists a neural network \( F^\theta_t = F^{\theta_t, \varepsilon, \tilde{\varepsilon}} \) such that
\[ \mathbb{P} \left( \left| F^\theta_t(Y_t) - B_t \right| > \tilde{\varepsilon} \right) < \varepsilon. \]
Define the sets \( A_1, A_2 \in \mathcal{F}_t \) by
\[ A_1 := \left\{ \omega \in \Omega : B_t(\omega) - \tilde{\varepsilon} \leq F^\theta_t(Y_t(\omega)) \leq B_t(\omega) + \tilde{\varepsilon} \right\}, \]
and
\[ A_2 := \left\{ \omega \in \Omega : B^\theta_{t-1} \tilde{\varepsilon} (\omega) \leq F^\theta_t(Y_t(\omega)) \right\}. \]
Then, \( \mathbb{P}(A_1) > 1 - \varepsilon \). Note that by the assumption of the induction
\[ B^\theta_{t-1} \tilde{\varepsilon} \leq B_{t-1} + \tilde{\varepsilon} \leq B_t + \tilde{\varepsilon} \quad \text{P-a.s.} \]
For \( A := A_1 \cap A_2 \) we have by construction,
\[ F^\theta_t(Y_t)1_{A} + B^\theta_{t-1} \tilde{\varepsilon} 1_{A^c} = F^\theta_t(Y_t)1_{A_1 \cap A_2} + B^\theta_{t-1} \tilde{\varepsilon} 1_{A_2^c \cup A_2} \in B^\theta_t, \tilde{\varepsilon}. \]
For \( \omega \in A_1 \cap A_2 \) we get that
\[ F^\theta_t(Y_t(\omega))1_{A_1 \cap A_2}(\omega) + B^\theta_{t-1} \tilde{\varepsilon} 1_{A_2^c}(\omega)1_{A_2^c}(\omega) = B^\theta_{t-1} \tilde{\varepsilon}(\omega) \]
and
\[ B_t(\omega) - \tilde{\varepsilon} \leq F^\theta_t(Y_t(\omega)) < B^\theta_{t-1} \tilde{\varepsilon}(\omega) \leq B_t(\omega) + \tilde{\varepsilon}. \]

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For $\omega \in A_1 \cap A_2$ we have

$$F^{\tilde{\vartheta}_t}(Y_t(\omega))1_{A_1 \cap A_2}(\omega) + B^{\theta_{t-1},\tilde{\epsilon}}(\omega)1_{A_1^c \cup A_2^c}(\omega) = F^{\tilde{\vartheta}_t}(Y_t(\omega))$$

and

$$\left| F^{\tilde{\vartheta}_t}(Y_t(\omega)) - B_t(\omega) \right| \leq \tilde{\epsilon}.$$ 

Thus, using that that $A_1 = (A_1 \cap A_2) \cup (A_1 \cap A_2^c)$ and $P(A_1) > 1 - \varepsilon$ we get

$$P \left( \left| \left( F^{\tilde{\vartheta}_t}(Y_t) 1_A + B^{\theta_{t-1},\tilde{\epsilon}}(\omega) 1_{A^c} \right) - B_t \right| > \tilde{\epsilon} \right) \leq P(A_t^c) < \varepsilon. \quad (4.9)$$

Then, (4.9) implies

$$P \left( B_t^{\theta_t,\tilde{\epsilon}} < B_t - \tilde{\epsilon} \right) \leq P \left( F^{\tilde{\vartheta}_t}(Y_t) 1_A + B^{\theta_{t-1},\tilde{\epsilon}}(\omega) 1_{A^c} < B_t - \tilde{\epsilon} \right) < \varepsilon. \quad (4.10)$$

Because $\varepsilon \in (0, 1)$ was arbitrary, it follows that $B_t \leq B_t^{\theta_t,\tilde{\epsilon}} + \tilde{\epsilon}$ $P$-a.s. by (4.10). By (4.8) and (4.10) we conclude that $|B_t^{\theta_t,\tilde{\epsilon}} - B_t| \leq \tilde{\epsilon}$ $P$-a.s. for all $t = 0, \ldots, T$. \hfill $\square$

## 5 Numerical results

In this section, we present some numerical applications for the results in Section 3 and 4. Combining Theorem 3.4 and 3.13, we obtain a two-step approximation for the superhedging price at $t = 0$. Then, we use Theorem 4.4 to simulate the superhedging process for $t > 0$.

### 5.1 Case $t = 0$

#### 5.1.1 Algorithm and implementation

Let $N \in \mathbb{N}$ denote a fixed batch size. For fixed $\lambda > 0$ we implement the following iterative procedure: for each iteration step $i$ we generate i.i.d. samples $Y(\omega_0^{(i)}), \ldots, Y(\omega_N^{(i)})$ of $Y$ and
consider the empirical loss function

\[ L_\lambda^{(i)}(\theta) = \left| F^{\theta} \left( \mathcal{Y}_0 \left( \omega_0^{(i)} \right) \right) \right|^2 + \frac{\lambda}{N} \sum_{j=1}^{N} l \left( H \left( \omega_j^{(i)} \right) \right) \]

\[ - \left[ F^{\theta} \left( \mathcal{Y}_0 \left( \omega_0^{(i)} \right) \right) + \sum_{k=1}^{T} F^{\theta_{k-1}} \left( \mathcal{Y}_{k-1} \left( \omega_{k-1}^{(i)} \right) \right) \cdot \left( X_k \left( \omega_k^{(i)} \right) - X_{k-1} \left( \omega_{k-1}^{(i)} \right) \right) \right] \],

with \( \theta = (\theta_1, \theta_2, \ldots, \theta_T) \). In the sequel we consider two possible choices for the function \( l : \mathbb{R} \to [0, \infty) \), i.e., the squared rectifier function

\[ l(x) = (\max \{x, 0\})^2, \quad (5.1) \]

or the truncated sigmoid function

\[ l(x) = \left( \max \left\{ \frac{1}{1 + e^{-x}} - \frac{1}{2}, 0 \right\} \right)^2, \quad (5.2) \]

see Figure 1 for the truncated sigmoid function. We then calculate the gradient of \( L_\lambda^{(i)}(\theta) \) at \( \theta^{(i)} \)

![Truncated sigmoid function](image)

**Figure 1:** Truncated sigmoid function (5.2).

and use it to update the parameters from \( \theta^{(i)} \) to \( \theta^{(i+1)} \) according to the *Adam* optimizer, see (Kingma & Ba, 2014). After sufficiently many iterations \( i \), we expect (see, e.g., (Goodfellow, Bengio, & Courville, 2016, Chapter 8) or (Buehler et al., 2019, Section 4.3)) that the loss \( L_\lambda(\theta^{(i)}) \)
is close to the minimal value of the loss function $L_\lambda$, where $L_\lambda$ is given by

$$
L_\lambda(\theta) = |F^{\theta_u}(Y_0)|^2 + \lambda \mathbb{E} \left[ l \left( H - \left( F^{\theta_u}(Y_0) + \sum_{k=1}^T F^{\theta_{k-1}}(Y_{k-1}) \cdot (X_k - X_{k-1}) \right) \right) \right].
$$

(5.3)

Note that $Y_0$ is constant and hence $F^{\theta_u}(Y_0)$ is a constant. We obtain a small value for the first term of $L_\lambda$ if $F^{\theta_u}(Y_0)$ representing the superhedging price is small. On the other hand, for our choices of $l$ the second summand in (5.3) is equal to 0 when the portfolio dominates the claim $H$. Thus, minimizing the second summand in (5.3) corresponds to maximizing the superhedging probability. When $l$ is given by the truncated sigmoid function (5.2) it is considered as an approximation of the indicator function which corresponds one to one to the method presented in Section 3. The weight $\lambda$ offers the opportunity to balance between a small initial price of the portfolio and a high probability of superhedging. The superhedging probability can always be estimated on a test set. In order to guarantee a given superhedging probability, we can re-train the network with a larger choice of $\lambda$ until the desired superhedging probability is achieved. In particular, if $\theta$ is the minimum for the loss function $L_\lambda(\theta)$, then $F^{\theta_u}(Y_0)$ is close to the minimal price required to superhedge the claim $H$ with a certain probability, i.e., to the quantile hedging price for a certain $\alpha = \alpha(\lambda)$. In view of Theorem 3.13 we thus expect $F^{\theta_u}(Y_0) \approx \inf \mathcal{U}_0$ for $\lambda$ large enough.

**Remark 5.1.** We note that also other choices for $l$ are possible as for instance the sigmoid function. However, the standard sigmoid function is very sensitive to the choice of $\lambda$ because it is strictly monotone on the complete real line. In general, for different choices of $l$ the stability in the learning process and the impact of $\lambda$ may vary. It appears to be important to choose a loss function that does not reward higher excess of the superhedging portfolio compared to a perfect hedge without excess.

The algorithm is implemented in Python, using Keras with backend TensorFlow to build and train the neural networks. More precisely, we create a *Sequential* object to build the models and compile with a customized loss function.

We use a Long-Short-Term-Memory network (LSTM), see (Hochreiter & Schmidhuber, 1997), with the following architecture: the network has two LSTM layers of size 30, which return sequences and one dense layer of size 1. Between the layers the *swish* activation function
is used. The activation functions within the LSTM layers are set to default, i.e., activation between cells is \( \text{tanh} \) and the recurrent activation is the \( \text{sigmoid} \) function. The kernel and bias initializer of the first LSTM layer are set to \( \text{truncated normal} \), i.e., the initial weights are drawn from a standard normal distribution but we discard and re-draw values, which are more than two standard deviations from the mean. This gives 11191 trainable parameters. The training is performed using the \( \text{Adam} \) optimizer with a learning rate of 0.001 or 0.0001. We generate 1024000 samples, which we split in 70\% for the training set and 30\% for the test set. The batch size is set to 1024. We apply the procedure described above in two examples, which we present in the following. The code is available at \url{https://github.com/tomrtsm/neural_network_approximation_for_superhedging_prices}.

### 5.1.2 Trinomial model

We consider a discrete time financial market model given by an arbitrage-free trinomial model with \( X_0 = 100 \) and

\[
X_t = X_0 \prod_{k=1}^t (1 + R_k), \quad t \in \{0, \ldots, T\},
\]

where \( R_t \) is \( \mathcal{F}_t \)-measurable for \( t \in \{1, \ldots, T\} \), and takes values in \( \{d, m, u\} \) with equal probability, where \(-1 < d < m < u\). Here, we set \( d = -0.01 \), \( m = 0 \), and \( u = 0.01 \) and \( T = 29 \) yielding \( 3^{29} \) possible paths. In this model, we want to superhedge a European Call option \( H = (X_T - K)^+ \) with strike price \( K = 100 \). For this choice of parameters the theoretical superhedging price is 2.17, as it can be easily obtained by Proposition 3.4 of (Carassus & Vargiolu, 2010).

The network is trained and evaluated for different \( \lambda \) to illustrate the impact of \( \lambda \) in (5.3) and the relation between \( \alpha(\lambda) \in (0, 1) \) and the corresponding \( \alpha(\lambda) \)-quantile hedging price. For each \( \lambda \) the network is trained over 40 epochs.

In Figure 2(a)-(c) for \( l \) given by (5.1) and Figure 3(a)-(c) for \( l \) given by (5.2), we see that \( \alpha(\lambda) \) as well as the \( \alpha(\lambda) \)-quantile hedging price increase in \( \lambda \), and that the \( \alpha(\lambda) \)-quantile hedging price increases in \( \alpha(\lambda) \). Figure 2(d) and Figure 3(d) show the superhedging performance on the test set for all \( \lambda \)'s, i.e., samples of

\[
F^{\theta_\alpha(\lambda)}(\mathcal{Y}_0) + \sum_{k=0}^T F^{\theta_{\alpha(\lambda)}}(\mathcal{Y}_{k-1}) \cdot (X_k - X_{k-1}) - H, \tag{5.4}
\]
for each \( \lambda \). Table 1 and Table 2 summarize the values for \( \lambda \), \( \alpha(\lambda) \) and the \( \alpha(\lambda) \)-quantile hedging price for \( l \) given by (5.1) and (5.2), respectively. In particular, for \( \lambda = 10000 \) we obtain a numerical price of \( 2.15 \) and \( \alpha(\lambda) = 99.24\% \) for \( l \) given by (5.1). For \( \lambda = 300000 \) we obtain a numerical price of \( 2.16 \) and \( \alpha(\lambda) = 99.69\% \) for \( l \) given by (5.2). Furthermore, the analysis shows that the impact of \( \lambda \) significantly depends on the choice of \( l \).

<table>
<thead>
<tr>
<th>( \lambda )</th>
<th>( \alpha(\lambda) )</th>
<th>( \alpha(\lambda) )-quantile hedging price</th>
</tr>
</thead>
<tbody>
<tr>
<td>10</td>
<td>15.23%</td>
<td>1.61</td>
</tr>
<tr>
<td>50</td>
<td>55.61%</td>
<td>1.81</td>
</tr>
<tr>
<td>100</td>
<td>70.75%</td>
<td>1.86</td>
</tr>
<tr>
<td>500</td>
<td>92.16%</td>
<td>1.96</td>
</tr>
<tr>
<td>1000</td>
<td>95.42%</td>
<td>2.00</td>
</tr>
<tr>
<td>2000</td>
<td>96.88%</td>
<td>2.04</td>
</tr>
<tr>
<td>4000</td>
<td>98.48%</td>
<td>2.09</td>
</tr>
<tr>
<td>10000</td>
<td>99.24%</td>
<td>2.15</td>
</tr>
</tbody>
</table>

Table 1: Impact of \( \lambda \) on \( \alpha(\lambda) \) and on the \( \alpha(\lambda) \)-quantile hedging price for \( l = (\max \{ x, 0 \})^2 \).

<table>
<thead>
<tr>
<th>( \lambda )</th>
<th>( \alpha(\lambda) )</th>
<th>( \alpha(\lambda) )-quantile hedging price</th>
</tr>
</thead>
<tbody>
<tr>
<td>1000</td>
<td>62.11%</td>
<td>1.82</td>
</tr>
<tr>
<td>5000</td>
<td>86.92%</td>
<td>1.92</td>
</tr>
<tr>
<td>10000</td>
<td>93.12%</td>
<td>1.96</td>
</tr>
<tr>
<td>50000</td>
<td>98.03%</td>
<td>2.04</td>
</tr>
<tr>
<td>75000</td>
<td>98.97%</td>
<td>2.07</td>
</tr>
<tr>
<td>100000</td>
<td>99.28%</td>
<td>2.08</td>
</tr>
<tr>
<td>150000</td>
<td>99.34%</td>
<td>2.10</td>
</tr>
<tr>
<td>300000</td>
<td>99.69%</td>
<td>2.16</td>
</tr>
</tbody>
</table>

Table 2: Impact of \( \lambda \) on \( \alpha(\lambda) \) and on the \( \alpha(\lambda) \)-quantile hedging price for \( l = \left( \max \left\{ \frac{1}{1+e^{-x}} - \frac{1}{2}, 0 \right\} \right)^2 \).

5.1.3 Discretized Black Scholes model

Here we consider a discrete time financial market for the asset price \( X \) given by a Black-Scholes model considered at discrete times \( th \) for \( t \in \{0, 1, \ldots, 30\} \) and \( h = \frac{1}{250} \). We consider a Barrier Up and Out Call option \( H = \prod_{t=0}^{T} 1_{(X_t < U)} (X_T - K)^+ \) with strike \( K = 100 \) and upper bound \( U = 105 \) such that \( K < U \) and \( X_0 < U \). We set \( X_0 = 100, \sigma = 0.3 \) and \( \mu = 0 \). We
Figure 2: Impact of $\lambda$ on the quantile hedging price and on the superhedging probability for $l = (\max \{x, 0\})^2$. 
Figure 3: Impact of $\lambda$ on the quantile hedging price and on the superhedging probability for $l = \left( \max \left\{ \frac{1}{1 + e^{-x}} - \frac{1}{2}, 0 \right\} \right)^2$. 
assume to have 250 trading days per year and a time horizon $T$ of 30 trading days with daily rebalancing. In particular, for a European contingent claim the time until expiration for the option is $\tau = 30/250$.

The weight $\lambda$ of the loss function is set to 10000000 in order to obtain a high superhedging probability. Indeed, we obtain a superhedging probability of 100% on the training set as well as on the test set with an approximate price of 3.73. By Table 1 in (Carassus et al., 2007), the theoretical superhedging price $\pi^H$ is given by

$$
\pi^H = X_0 \left( 1 - \frac{K}{U} \right) \approx 4.76.
$$

In the Black-Scholes model the asset price process at time $t > 0$ has unbounded support and thus the additional error, which arises from the discretization of the probability space, is non-negligible. Although the Barrier option artificially bounds the support of the model, the numerical price still significantly deviates from the theoretical price.

Finally, we consider a European call option $H = (X_T - K)^+$ with strike $K = 100$ and parameters $X_0 = 100$, $\sigma = 0.1$ and $\mu = 0$. By (Carassus et al., 2007) the theoretical price of $H$ for the discrete time version of the Black-Scholes model is equal to $X_0 = 100$. The theoretical price of $H$ in a standard Black-Scholes model in the continuous time is 1.38, and by following the $\delta$-hedging strategy we superhedge $H$ with a probability of 53.69%. We first choose $l$ given by (5.1). Here we consider $\lambda = 50$ in (5.3) in order to compare the result to the discretized $\delta$-hedging strategy of the Black-Scholes model, and $\lambda = 10000$ in order to obtain a high superhedging probability. For $\lambda = 50$, we obtain an approximate price of 1.41 and a superhedging probability of 54.43%.

In Figure 4(a) we compare the $\delta$-hedging strategy with the approximated superhedging strategy obtained for $\lambda = 50$. Further, in Figure 4(b) we compare the results for $\lambda = 50$ and $\lambda = 10000$, respectively. For $\lambda = 10000$, the superhedging probability on the test set is 99.79% with an approximated price of 2.18.

For $l$ given by (5.2) we obtain for $\lambda = 10000$ a superhedging probability of 99.66% and a price of 2.10. Again, we can see the different impact of $\lambda$ for different choices of $l$ in (5.3).
(a) $\delta$-hedging strategy compared to approximate strategy for $\lambda = 50$

(b) Approximate strategy for $\lambda = 50$ and $\lambda = 10000$

Figure 4: Hedging losses for $\lambda = 50$, $\lambda = 10000$ and for the $\delta$-hedging strategy.

5.2 Case $i > 0$

In this section we approximate the process of consumption by neural networks as proposed in Section 4.2. We implement the same iterative procedure as introduced in Section 5.1.1. We define $G^{(i)}$ as the difference of the approximated superhedging strategy obtained from Section 5.1 and the claim $H$, i.e.,

$$G^{(i)}_j (\theta^*) := \left[ F_{\theta^*_j} \left( Y_0 \left( \omega^{(i)}_j \right) \right) + \sum_{k=1}^T F_{\theta^*_k, \omega^{(i)}_j} \left( Y_{k-1} \left( \omega^{(i)}_j \right) \right) \cdot \left( X_k \left( \omega^{(i)}_j \right) - X_{k-1} \left( \omega^{(i)}_j \right) \right) - H \left( \omega^{(i)}_j \right) \right].$$

Then, the empirical loss function is given by

$$\hat{L}^{(i)}_{t, \beta} (\theta_t) = \frac{1}{N} \sum_{j=1}^N - \left| B^{\theta_t} \left( \omega^{(i)}_j \right) \right|^2 + \beta \max \left\{ \left( B^{\theta_t} \left( \omega^{(i)}_j \right) - G^{(i)}_j (\theta^*) \right), 0 \right\},$$

40
where $B^{θ_t}$ is given by
\[ B^{θ_t} (\omega_j^{(i)}) := \max \left\{ F^{θ_t} (Y_t (\omega_j^{(i)})), B^{θ_t-1} (\omega_j^{(i)}) \right\}. \]

At a local minimum the two terms of $L$ guarantee that $F^{θ_t}$ is as big as possible but less or equal than $G(θ^*)$.

Here, we also consider a discretized Black-Scholes model as in Section 5.1.3 but only a time horizon of 10 trading days and set $X_0 = 100$, $σ = 0.1$ and $μ = 0$. For each $t > 0$ the neural network consists of two LSTM layers of size 30 and 20 respectively, which return sequences, one LSTM layer of size 20 providing one single value and one dense layer of size 1. The remaining parameters are chosen as in Section 5.1.1.

As in Section 5.1.3, we compute an approximated superhedging price and strategy for the complete interval. Setting $λ = 1024$ yields an approximated price of 1.35 and a superhedging probability of 98.87% for $t = 0$. For $t ≥ 1$, we choose $β = 500$ and then obtain a superhedging probability of 98.78%. In Figure 5(a), we show trajectories of the approximated superhedging price process generated by this method. Figure 5(b) illustrates paths given by the $δ$-hedging strategy of the discretized Black-Scholes model. Finally, we plot the difference of the approximated superhedging price processes and the corresponding price process obtained by the $δ$-hedging strategy in Figure 5(c).

### 5.3 Discussion

In finite market models as in Section 5.1.2, our methodology delivers an approximation of $α$-quantile hedging and approximated superhedging prices with small approximation error. It is also worth noting, that the predicted superhedging price and the corresponding superhedging probability of the training set are consistent with the values on the test set.

In contrast, in models in which the price process has unbounded support, our numerical results indicate that the additional error caused by the discretization of the probability space cannot be ignored. However, we obtain consistent results of the $α$-quantile hedging price for the training set and test set. Note also that, in Section 5.1.3, the Barrier option can be superhedged with 100% on the training and on the test set.
Figure 5: Superhedging price process compared to the \( \delta \)-hedging price process.
A further possible application of our methodology is given by superhedging in a model-free setting on prediction sets, see (Bartl et al., 2020), (Bartl et al., 2019), (Hou & Oblój, 2018), where prediction sets offer the opportunity to include beliefs in price developments or to select relevant price paths.

References


Cuchiero, C., Khosravi, W., & Teichmann, J. (2020). A generative adversarial net-


A Proof of Proposition 3.2

Proof. “ ≤ ”: Take $A \in \mathcal{F}_T$ such that $P(A) \geq \alpha$. We prove that

$$\sup_{P^* \in P} E^*[H 1_A] \in \left\{ u \in \mathbb{R} : \exists \xi \text{ adm. s.t. } P \left( u + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) \geq H \right) \geq \alpha \right\}. \quad (A.1)$$

By the well-known superhedging duality, see Theorem 7.13 of (Föllmer & Schied, 2016), we have that

$$\sup_{P^* \in P} E^*[H 1_A] = \inf \left\{ u \in \mathbb{R} : \exists \xi \text{ pred. s.t. } u + \sum_{k=1}^{T} \xi_k \cdot (X_k - X_{k-1}) \geq H 1_A \ P\text{-a.s.} \right\},$$

and that there exists a superhedging strategy $\hat{\xi}$ for $H 1_A$ with initial value $\sup_{P^* \in P} E^*[H 1_A]$, i.e.,

$$\sup_{P^* \in P} E^*[H 1_A] + \sum_{k=1}^{T} \hat{\xi}_k \cdot (X_k - X_{k-1}) \geq H 1_A \geq 0 \ P\text{-a.s.} \quad (A.2)$$

In particular, by (A.2) we get for $\hat{\xi}$ that

$$P \left( \sup_{P^* \in P} E^*[H 1_A] + \sum_{k=1}^{T} \hat{\xi}_k \cdot (X_k - X_{k-1}) \geq H \right) \geq P(A) \geq \alpha. \quad (A.3)$$

This implies (A.1) and hence

$$\inf U_0^\alpha \leq \inf \left\{ \sup_{P^* \in P} E^*[H 1_A] : A \in \mathcal{F}_T, P(A) \geq \alpha \right\}. \quad (A.4)$$

“ ≥ ”: Take $\bar{u} \in U_0^\alpha$ and denote by $\hat{\xi} = (\hat{\xi}_k)_{k=1}^{T}$ the corresponding strategy such that

$$P \left( \bar{u} + \sum_{k=1}^{T} \hat{\xi}_k \cdot (X_k - X_{k-1}) \geq H \right) \geq \alpha. \quad (A.5)$$

Define the set $\tilde{A}$ by

$$\tilde{A} := \left\{ \omega \in \Omega : \bar{u} + \sum_{k=1}^{T} \hat{\xi}_k(\omega) \cdot (X_k(\omega) - X_{k-1}(\omega)) \geq H(\omega) \right\}. \quad (A.6)$$

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Clearly $\tilde{A} \in \mathcal{F}_T$ and $P(\tilde{A}) \geq \alpha$. By construction we have that

$$\left( \tilde{u} + \sum_{k=1}^{T} \tilde{\xi}_k \cdot (X_k - X_{k-1}) \right) \mathbb{1}_{\tilde{A}} \geq H \mathbb{1}_{\tilde{A}} \text{ P-a.s.}$$

and because $\tilde{\xi}$ is assumed to be admissible, we have

$$\left( \tilde{u} + \sum_{k=1}^{T} \tilde{\xi}_k \cdot (X_k - X_{k-1}) \right) \mathbb{1}_{\tilde{A}^c} \geq 0 \text{ P-a.s.}$$

In particular, $\tilde{u} \in \mathcal{U}_0(\mathbb{1}_{\tilde{A}})$ and by Theorem 7.13 of (Föllmer & Schied, 2016) we obtain

$$\tilde{u} \geq \sup_{\mathbb{P}^* \in \mathcal{P}} \mathbb{E}^* [\mathbb{1}_{\tilde{A}}] \in \left\{ \sup_{\mathbb{P}^* \in \mathcal{P}} \mathbb{E}^* [\mathbb{1}_A] : A \in \mathcal{F}_T, \ P(A) \geq \alpha \right\}. \quad (A.3)$$

That is, for an arbitrary $\tilde{u} \in \mathcal{U}_0^{\alpha}$ we have constructed a set $\tilde{A}$ such that (A.3) holds. Therefore,

$$\inf \mathcal{U}_0^{\alpha} \geq \inf \left\{ \sup_{\mathbb{P}^* \in \mathcal{P}} \mathbb{E}^* [\mathbb{1}_A] : A \in \mathcal{F}_T, \ P(A) \geq \alpha \right\}.$$

\[\square\]

**B Neural Networks**

For the reader’s convenience we recall some results on neural networks. The following result essentially follows from (Hornik, 1991, Theorem 1). For completeness we include its proof here.

**Theorem B.1.** Assume $\sigma$ is bounded and non-constant. Let $f : (\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d)) \rightarrow (\mathbb{R}^m, \mathcal{B}(\mathbb{R}^m))$ be a measurable function and $\mu$ be a probability measure on $(\mathbb{R}^d, \mathcal{B}(\mathbb{R}^d))$. Then for any $\varepsilon, \tilde{\varepsilon} > 0$ there exists a neural network $g$ such that

$$\mu(\{x \in \mathbb{R}^d : \|f(x) - g(x)\| > \tilde{\varepsilon}\}) < \varepsilon.$$

**Proof.** Let $\varepsilon, \tilde{\varepsilon} > 0$ be given and let $C > 0$ satisfy that

$$\mu(\{x \in \mathbb{R}^d : \|f(x)\| > C\}) < \frac{\varepsilon}{2}. \quad (B.1)$$

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Define \( \tilde{f} = I_{\{x \in \mathbb{R}^d : \|f(x)\| \leq C\}} f \). Then \( \tilde{f} \in L^1(\mathbb{R}^d, \mu) \) and hence (Hornik, 1991, Theorem 1) shows that there exists a neural network \( g \) with

\[
\int_{\mathbb{R}^d} \|\tilde{f}(x) - g(x)\| \mu(dx) < \frac{\varepsilon \varepsilon}{4}.
\]

Markov’s inequality thus proves that

\[
\mu(\{x \in \mathbb{R}^d : \|\tilde{f}(x) - g(x)\| > \frac{\varepsilon}{2}\}) \leq \frac{2}{\varepsilon} \int_{\mathbb{R}^d} \|\tilde{f}(x) - g(x)\| \mu(dx) < \frac{\varepsilon}{2}.
\]

Combining (B.1) and (B.2) and recalling \( f - \tilde{f} = f I_{\{x \in \mathbb{R}^d : \|f(x)\| > C\}} \) yields

\[
\mu(\{x \in \mathbb{R}^d : \|f(x) - g(x)\| > \varepsilon\}) \leq \mu(\{x \in \mathbb{R}^d : \|f(x) - \tilde{f}(x)\| > \frac{\varepsilon}{2}\} \cup \{x \in \mathbb{R}^d : \|\tilde{f}(x) - g(x)\| > \frac{\varepsilon}{2}\})
\]

\[
< \mu(\{x \in \mathbb{R}^d : \|f(x)\| > C\}) + \frac{\varepsilon}{2} < \varepsilon.
\]

\[\square\]

C Further results

**Theorem C.1** (Theorem A.37, (Föllmer & Schied, 2016)). Let \( \Phi \) be any set of random variables on \((\Omega, \mathcal{F}, P)\).

1. There exists a random variable \( \varphi^* \) with the following two properties.

   (a) \( \varphi^* \geq \varphi \) \( P \)-a.s. for all \( \varphi \in \Phi \).

   (b) \( \varphi^* \leq \psi \) \( P \)-a.s. for every random variable \( \psi \) satisfying \( \varphi \geq \varphi \) \( P \)-a.s. for all \( \varphi \in \Phi \).

2. Suppose in addition that \( \Phi \) is directed upwards, i.e., for \( \varphi, \hat{\varphi} \in \Phi \) there exists \( \psi \in \Phi \) with \( \psi \geq \varphi \vee \hat{\varphi} \). Then there exists an increasing sequence \( \varphi_1 \leq \varphi_2 \leq \ldots \in \Phi \) such that \( \varphi^* = \lim_{n \to \infty} \varphi_n \) \( P \)-a.s.

**Definition C.2** (Definition A.38, (Föllmer & Schied, 2016)). The random variable \( \varphi^* \) in Theorem C.1 is called the essential supremum of \( \Phi \) with respect to \( P \), and we write

\[
\text{ess sup} \Phi = \text{ess sup}_{\varphi \in \Phi} \varphi := \varphi^*.
\]

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The essential infimum of $\Phi$ with respect to $P$ is defined as

$$\text{ess inf } \Phi = \text{ess inf } := -\text{ess sup } (-\varphi).$$

For random variables $(\xi_n)_{n \in \mathbb{N}} \subset L^0(\Omega, \mathcal{F}, P; \mathbb{R}^d)$ we denote by $\text{conv}\{\xi_1, \xi_2, \ldots\}$ the convex hull of $\xi_1, \xi_2, \ldots$ which is defined $\omega$-wise.

**Lemma C.3** (Lemma 1.70, (Föllmer & Schied, 2016)). Let $(\xi_n)_{n \in \mathbb{N}}$ be a sequence in $L^0(\Omega, \mathcal{F}, P; \mathbb{R}^d)$ such that $\sup_{n \in \mathbb{N}} |\xi_n| < \infty$ $P$-a.s. Then there exists a sequence of convex combinations

$$\eta_n \in \text{conv}\{\xi_n, \xi_{n+1}, \ldots\}, \quad n \in \mathbb{N},$$

which converges $P$-almost surely to some $\eta \in L^0(\Omega, \mathcal{F}, P; \mathbb{R}^d)$. 